

Progress Report for Year 2

College of William and Mary Algorithms and software

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The SOW points

Summary table of tasks to be performed at the College of William and Mary
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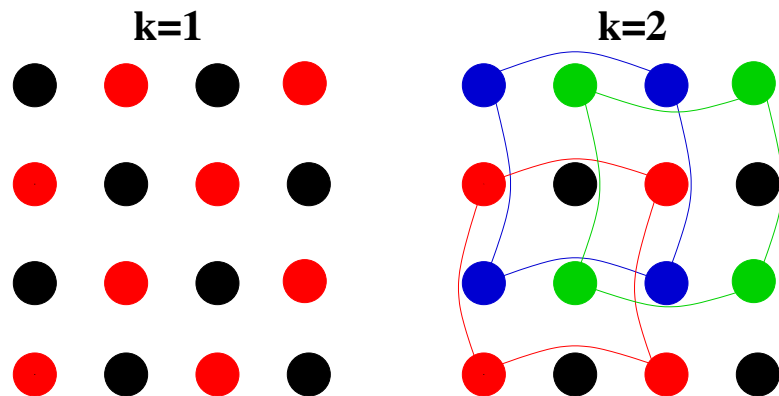
Year	Task	subtopic
1	Update the PRIMME eigenvalue package and provide a Level 3 interface callable from high level LQCD software packages	algorithms
2	Implement deflated Monte Carlo trace estimators	algorithms
3	Explore variance reducing vector samples	algorithms
4	Provide methods and implementations that combine deflation and variance reducing vectors	algorithms
3-5	Integrate the variance reduction mechanisms with effective preconditioners developed by the LQCD community	algorithms

Main theme **Variance Reduction (VR)** for $\mathbf{Tr}(A^{-1})$

- Extended hierarchical probing (SIAM SISC) to arbitrary lattice sizes
- Use of singular values for VR through eigCG
- Accurate solution of singular values with PRIMME
- Continued VR based on extrapolation techniques



●	●	●	●	●	●	●	●	k=1	1D:
0	2	1	3	0	2	1	3	k=2	Doubling k splits grid to 2 1D subgrids
0	2	1	3	4	7	5	8	k=4	Color R-B each with two new colors



2D:
 Doubling k splits grid to 4 2D subgrids
 (e.g., Reds split to 4 reds and 4 greens)
 Color R-B each with two new colors

Algorithm in d -dimensions:

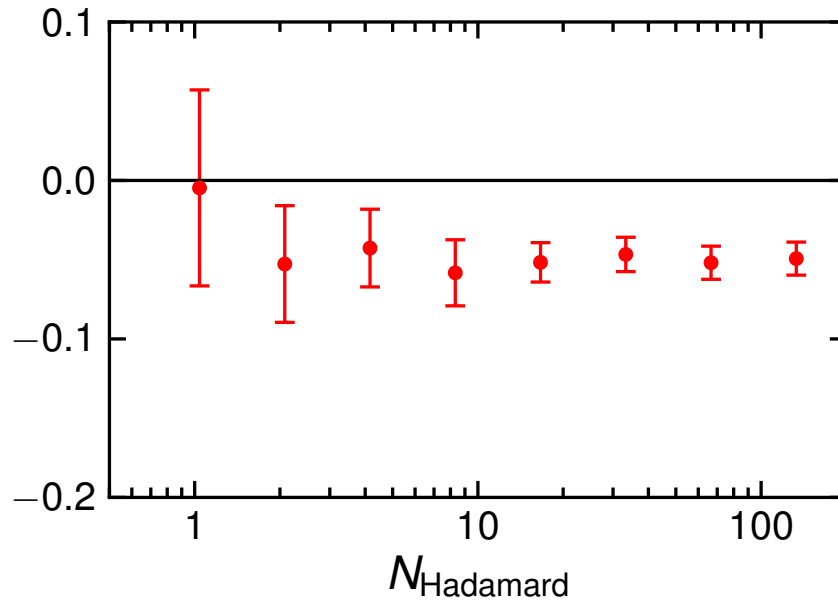
1. Recursively split a lattice $\prod_{i=1}^d 2^{c_i}$ to 2^d sublattices of size $\prod_{i=1}^d 2^{c_i-1}$
2. When no further splits possible, Red-Black each sublattice with unique colors
3. Choose unique colors appropriately to guarantee nesting

This only worked for powers of two sized lattices

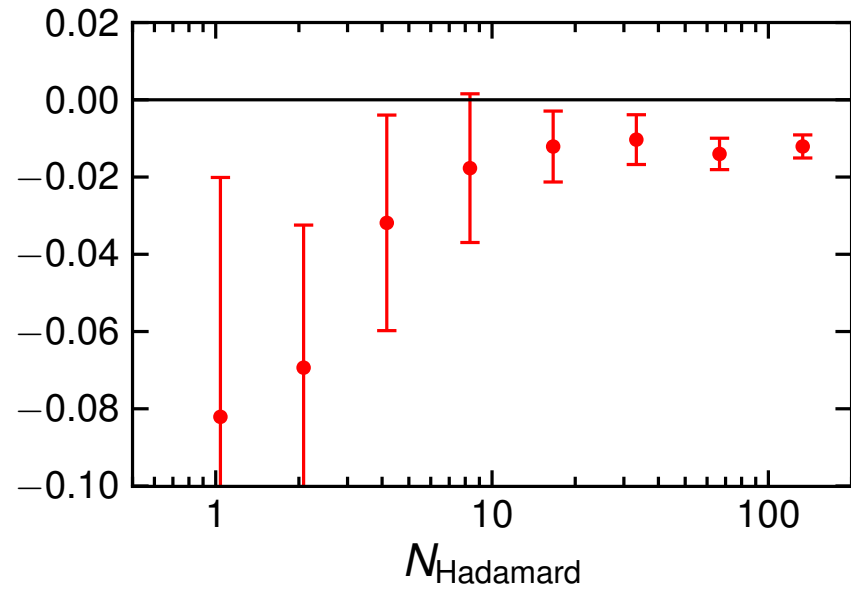


Hierarchical Probing results from Stefan Meinel

$G_A^{(u)} (Q^2 = 0)$ (disconnected, bare)



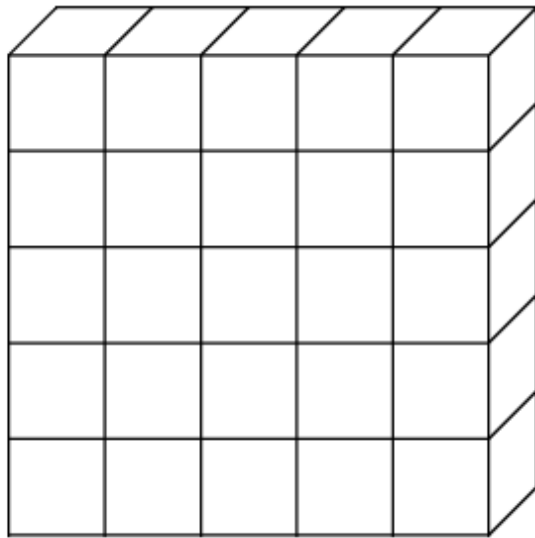
$G_M^{(\frac{2}{3}u - \frac{1}{3}d)} (Q^2 \approx 0.11 \text{ GeV}^2)$ (disconnected)



Error std ≈ 4 , thus speedups of about 16

Code available in Chroma





$$l_1 = 6 = 2 \cdot 3$$

$$l_2 = 6 = 2 \cdot 3$$

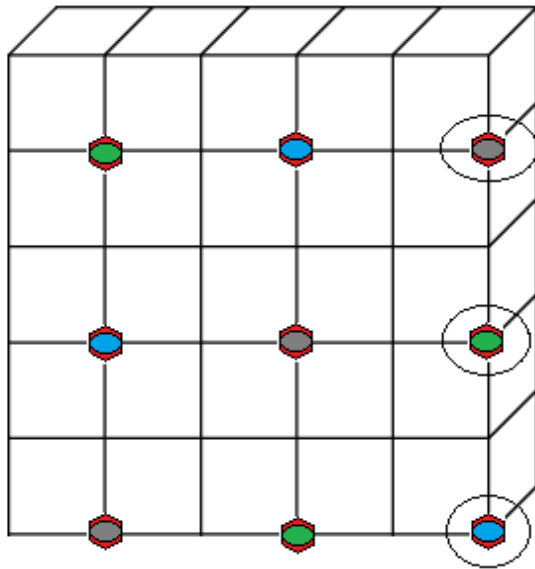
$$l_3 = 2$$

Consider a d -dimensional lattice with dimension lengths of l_1, l_2, \dots, l_d .

1. Find the common factors (eg. 2, 3 in Figure)
2. Split lattice into sub-lattices. Use common factors to determine which sub-lattice a point lies in
3. Assign each sub-lattice a color
4. Apply recursively until no more common factors
5. Color final sub-lattice with three colors



How to determine which sub-lattice a node lies in



(5,4,0)
in mixed radix representation
 $\langle 1, 2 \rangle_{2,3} \langle 0, 2 \rangle_{2,3} \langle 0 \rangle_2$

(5,2,0)
in mixed radix representation
 $\langle 1, 2 \rangle_{2,3} \langle 0, 1 \rangle_{2,3} \langle 0 \rangle_2$

(5,0,0)
in mixed radix representation
 $\langle 1, 2 \rangle_{2,3} \langle 0, 0 \rangle_{2,3} \langle 0 \rangle_2$

```

function subLattices = SplitLattice( latticeNodes, SplitLevel)
for n = 1 : numNodes
    for j = 1 : dims
        mixedrep(j) = dec2mixed(GetCoordOfLatticeNode(j,n))
        subLattices(mixedrep(1)(1 : SplitLevel), ..., mixedrep(d)(1 : SplitLevel)) = latticeNode(n)
        % Nodes that have the same 1:SplitLevel digits are in the same sublattice
    for j = 1 : numSublattices
        AssignColorToLattice(subLattices(j))
        SplitLattice(subLattices(j), SplitLevel + 1)
    endfor
    endfor

```



Creating Probing Vectors

Let c_i be the number of colors needed to color the sublattices of a lattice after i recursive calls

Then we can create the probing matrix as below

$$\begin{aligned}\tilde{Z}^{(1)} &= F_{c(1)}, \\ \tilde{Z}^{(i)} &= \left[\tilde{Z}^{(i-1)} \otimes F_{c(i)}(:, 1), \dots, \tilde{Z}^{(i-1)} \otimes F_{c(i)}(:, c(i)) \right]\end{aligned}$$

To generate a probing vector (column of $Z^{(i)}$) only two vectors are needed:

one from $\tilde{Z}^{(i-1)}$, $i > 1$

and one from a $F_{c(j)}$.

Vectors of $\tilde{Z}^{(i-1)}$ are obtained recursively



Creating Probing Vectors

Take the list $c(i)$ containing the number of colors needed per lattice after i splits

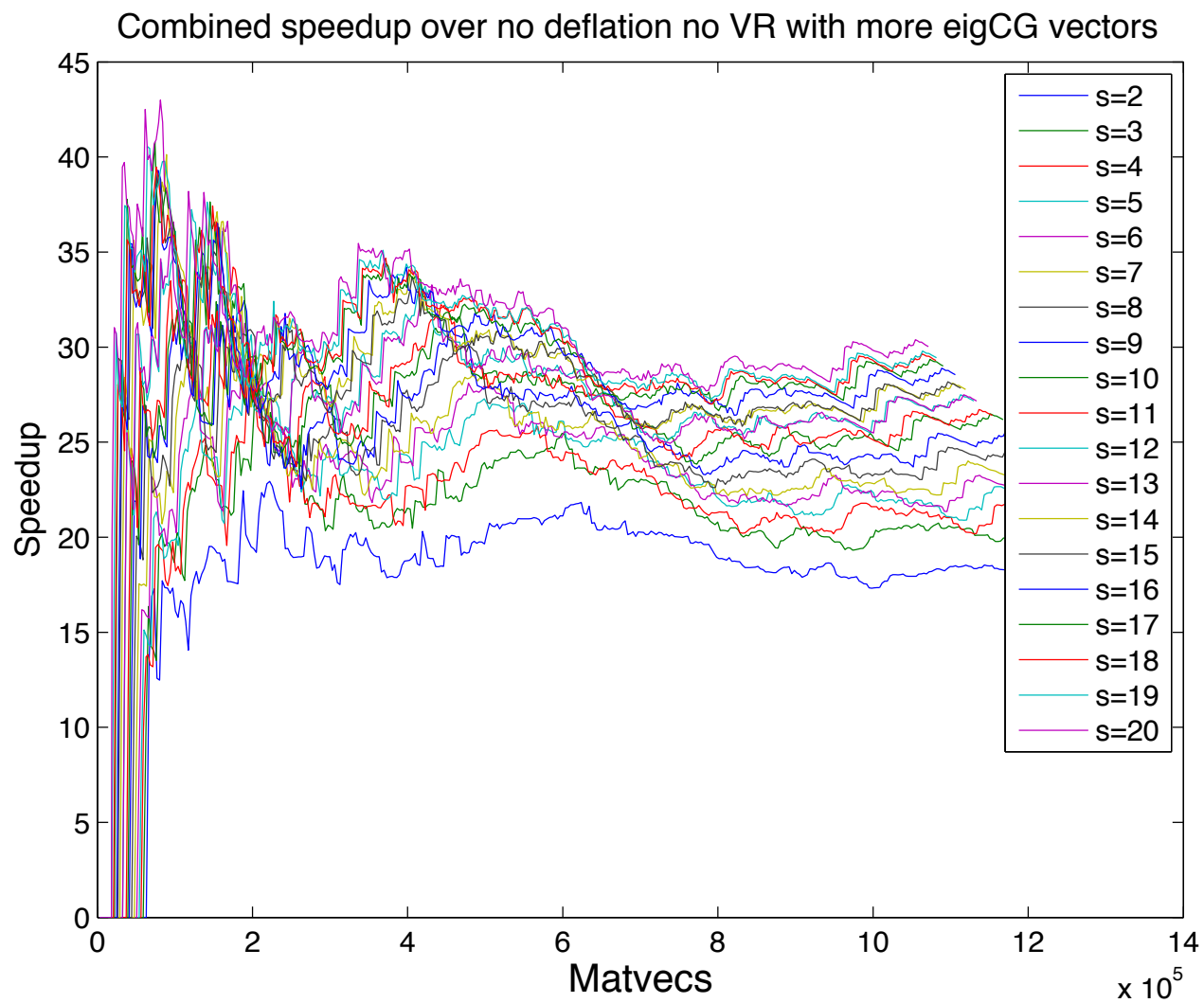
Interpret $c(i)$ as a mixed-radix base

For the k -th probing vector, the required vectors of F_{c_1}, F_{c_2}, \dots , are the n digits for the mixed radix representation of k using this mixed-radix base

$$\mathbf{F}_2 = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}, \mathbf{F}_3 = \begin{pmatrix} 1 & 0 & 0 \\ 1 & (-1)^{4/3} & (-1)^{2/3} \\ 1 & (-1)^{2/3} & (-1)^{4/3} \end{pmatrix} \quad (1)$$

If $\mathbf{c} = \{2, 3\}$, then for $k=2$ the mixed radix representation of k is $\langle 0, 1 \rangle_{2,3}$, and $F_2(:, 1) \otimes F_3(:, 2)$ produces the required vector





Good speedups with only 7-8 rhs of eigCG



Find k **smallest singular triplets** of a large, sparse matrix $A \in \mathfrak{R}^{m \times n}$

$$Av_i = \sigma_i u_i, \quad \sigma_1 \leq \dots \leq \sigma_k$$

- A Hermitian eigenvalue problem on
 - Normal equations matrix $C = A^T A$ or $C = AA^T$
 - Augmented matrix $B = \begin{pmatrix} 0 & A^T \\ A & 0 \end{pmatrix}$
- Lanczos bidiagonalization method (LBD)

$$A = PB_d Q^T$$

$$B_d = X \Sigma Y^T$$

Where $U = PX$ and $V = QY$



Motivation I: difference between methods

- Eigen methods on C
 - fast for largest SVs
 - slow for smallest SVs
 - can only achieve accuracy of $O(\kappa(A)\|A\|\epsilon_{mach})$
- Eigen methods on B
 - slower for largest SVs
 - extremely slow for smallest SVs
 - can achieve accuracy of $O(\|A\|\epsilon_{mach})$
- LBD on A
 - fast for largest SVs
 - similar to C but exhibits irregular convergence
 - can achieve accuracy of $O(\|A\|\epsilon_{mach})$



Motivation II: our goal for an SVD solver

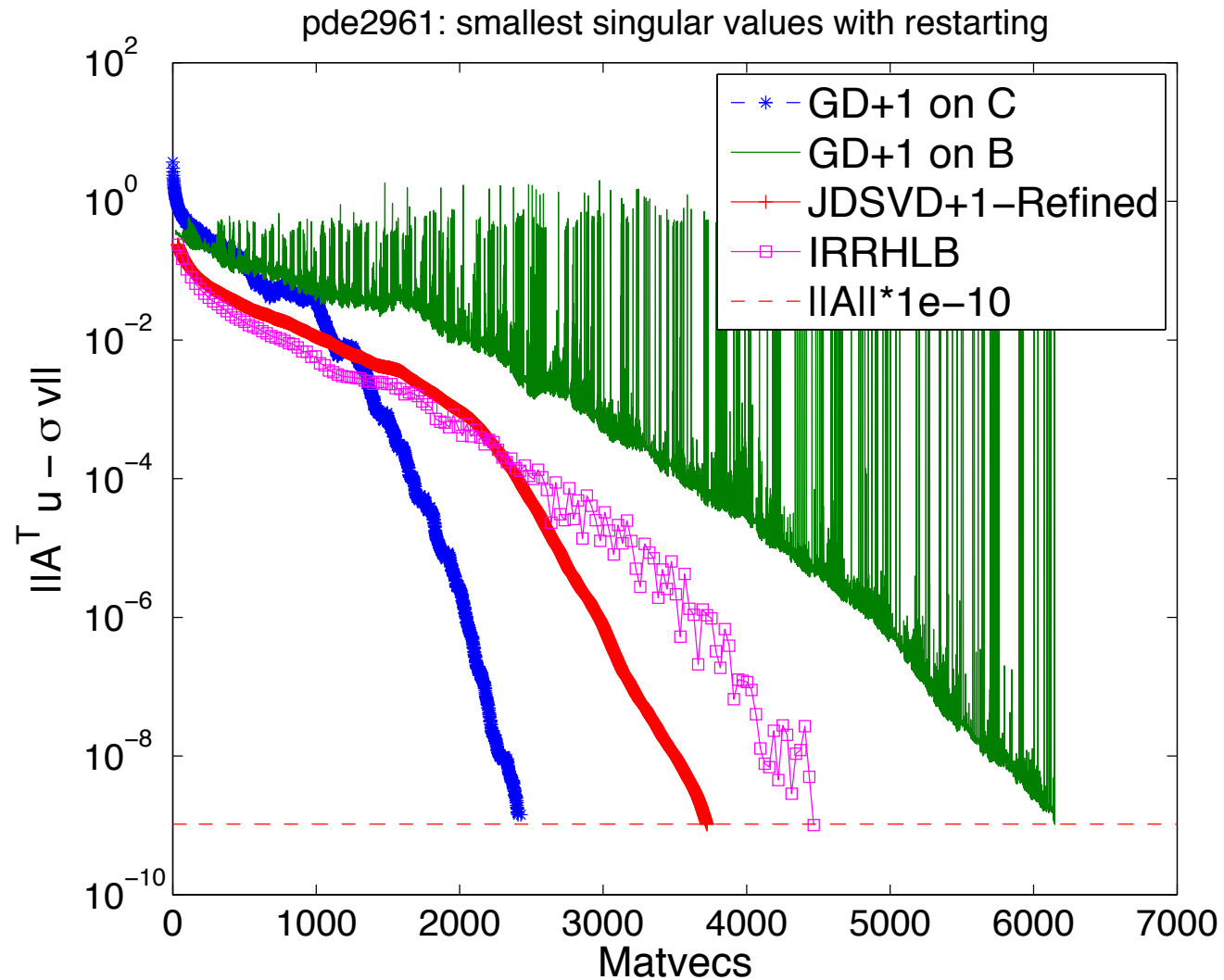
Extremely challenging task for small SVs:

- large sparse matrix \Rightarrow **No shift-and-invert**
 - very slow convergence \Rightarrow **restarting** and **preconditioning**
 - very few SVD solvers:
 - SVDPACK: Lanczos/trace-min methods on B or C for only largest SVs
 - PROPACK: LBD for largest SVs. Shift-invert for smallest SVs
- \Rightarrow **calls for full functionality, highly-optimized SVD solver**

PRIMME: PReconditioned **I**terative **M**ulti**M**ethod **E**igensolver



Motivation III: the impact of restarting



primme_svds: a two stage strategy

Our solution: a hybrid, two-stage SVD method

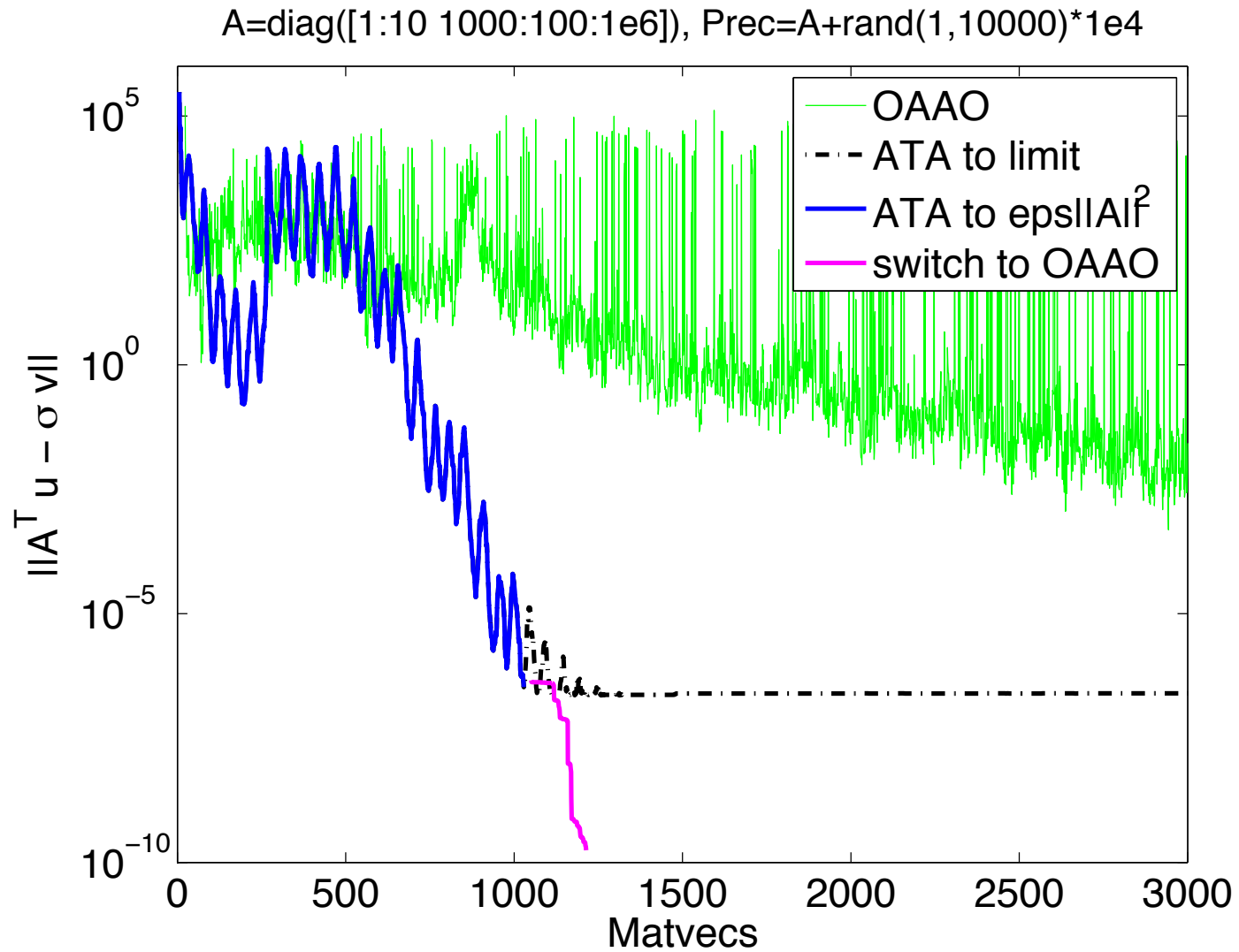
- Stage I: works on C to max residual tolerance $\max(\sigma_i \delta_{user} \|A\|, \|A\|^2 \epsilon_{mach})$
 - Must dynamically adjust tolerance in PRIMME to meet user tolerance
- Stage II: works on B to improve the approximations from C until user required tolerance $\delta_{user} \|A\|$ is satisfied
 - Inputs from C : accurate shifts and good initial guesses
 - ⇒ Calls for near-optimal method JDQMR in PRIMME
 - Irregular convergence of Rayleigh Ritz (RR) on B
 - ⇒ Enhance PRIMME with refined projection method

Refined projection minimizes the residual $\|BVy - \tilde{\sigma}Vy\|$ where V search space for a given user shift $\tilde{\sigma}$

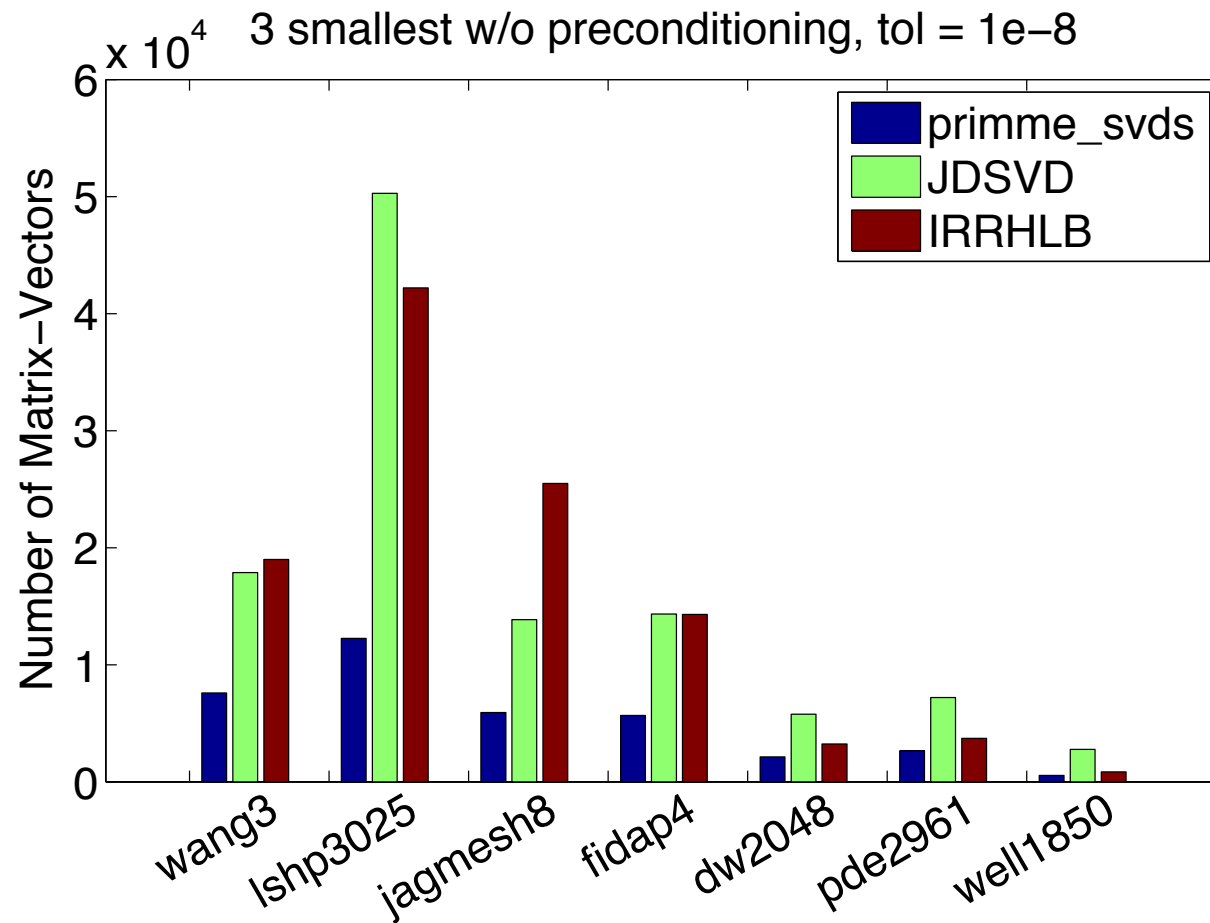
- QR factorization on $BV - \tilde{\sigma}V$ only after restart
- one column updating for Q and R during iteration
- computational cost similar with the RR method



primme_svds: an example



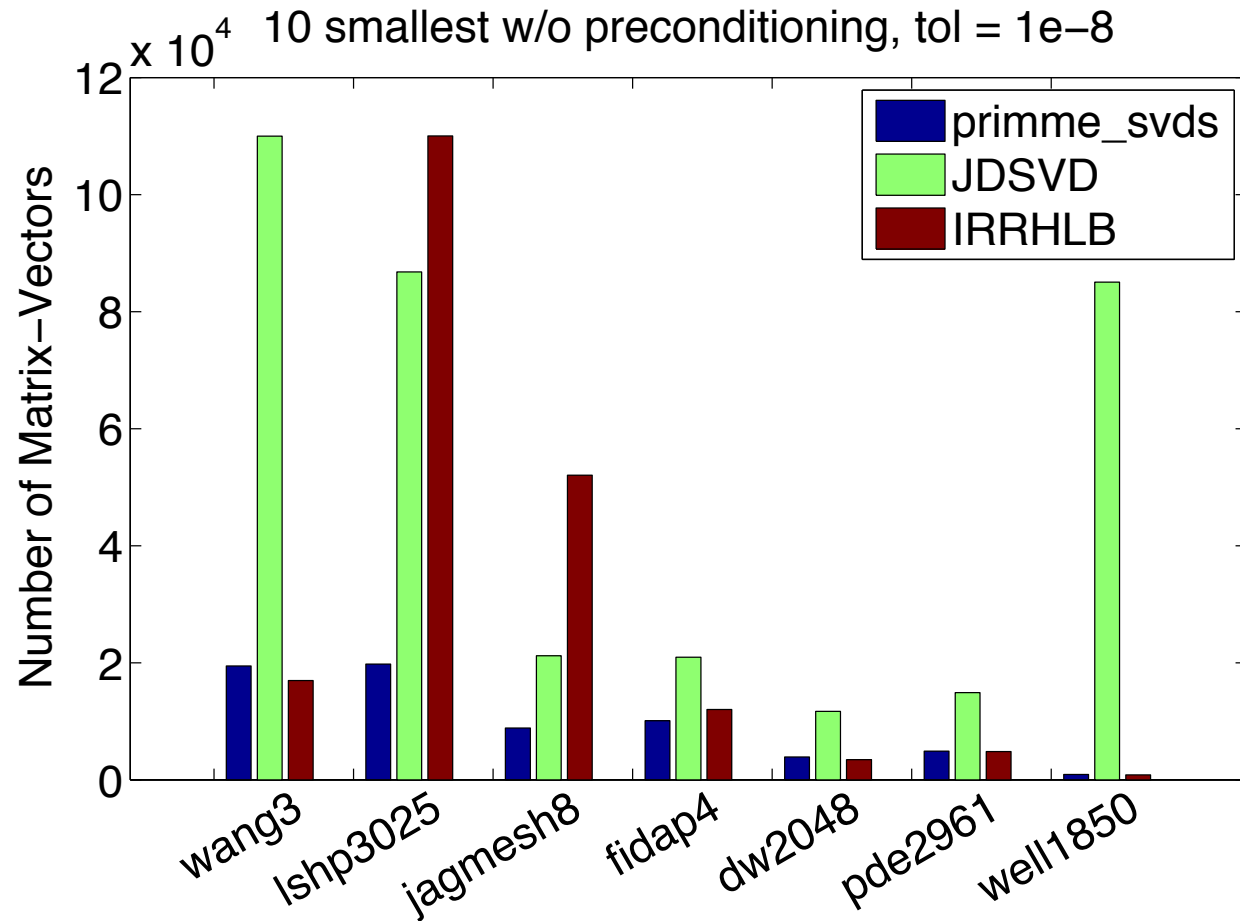
Evaluation: Without preconditioning



primme_svds (only first stage) is the fastest method



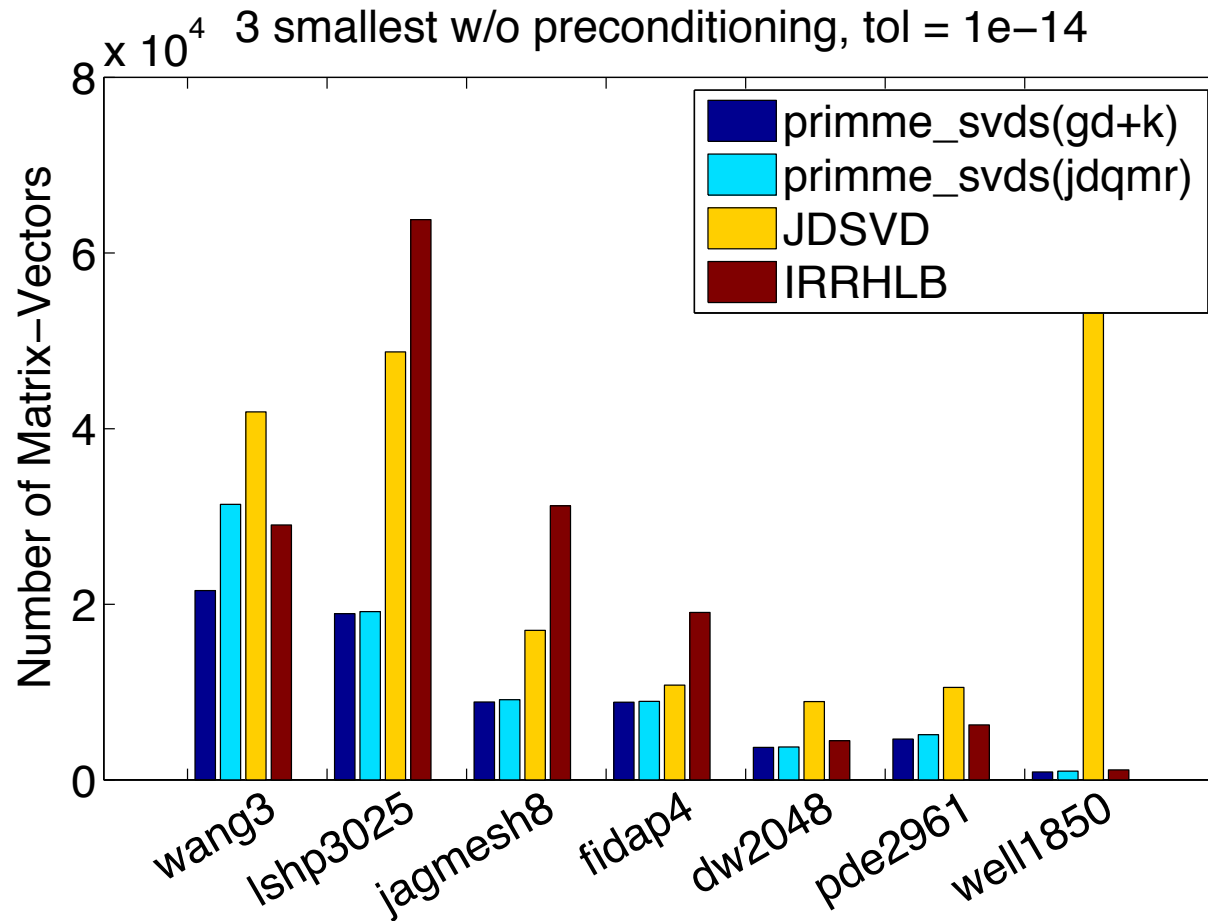
Evaluation: Without preconditioning



primme_svds (only first stage) is much faster in hard cases



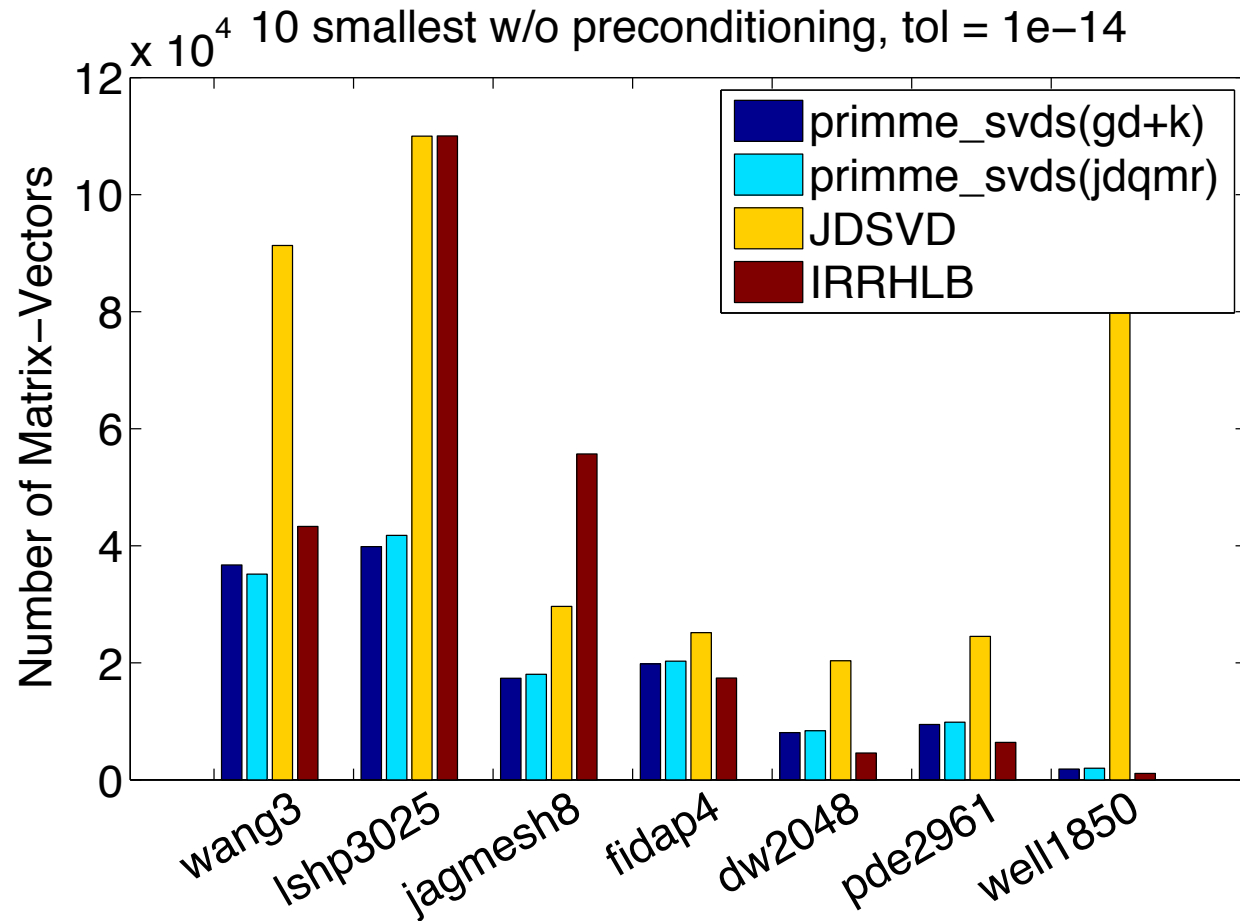
Evaluation: Without preconditioning



primme_svds (two stage) is superior for a few singular triplets



Evaluation: Without preconditioning



primme_svds (two stage) is much faster in hard cases

