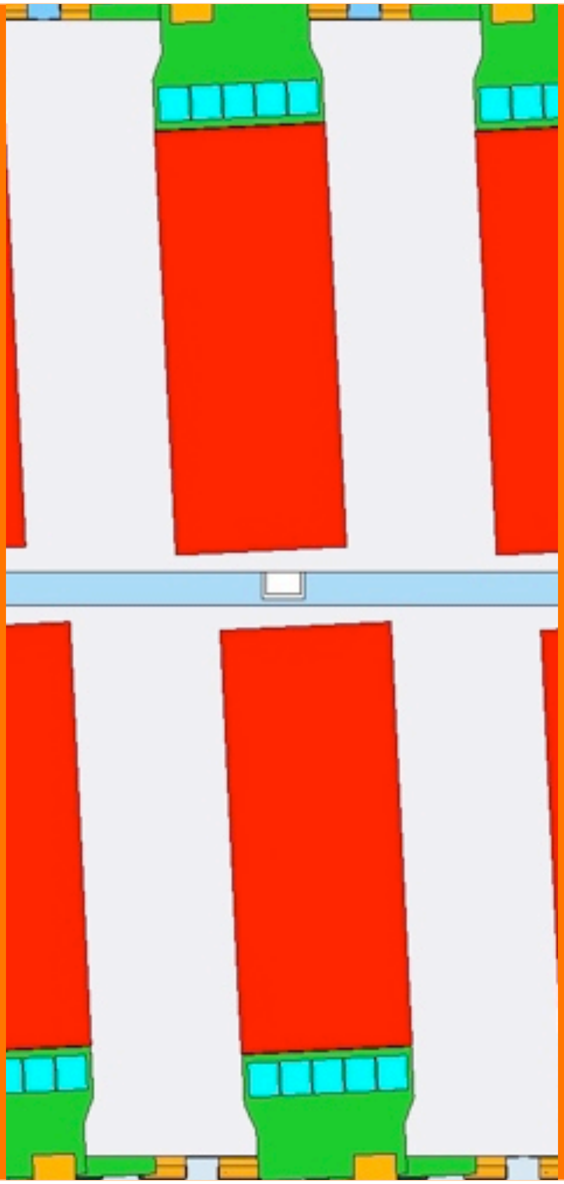


HPS Tracking and Vertexing System

***Tim Nelson* - SLAC**

Boson 2010, JLab

September 20, 2010

The Elevator Pitch

Our sensitivity relies upon abilities to *precisely*...

- determine invariant mass of A' decay products (estimate momentum vectors)
- distinguish A' decay vertexes as non-prompt (extrapolate tracks to origin)

"If they don't like our proposal I'll show them the kittens. Everybody likes kittens."

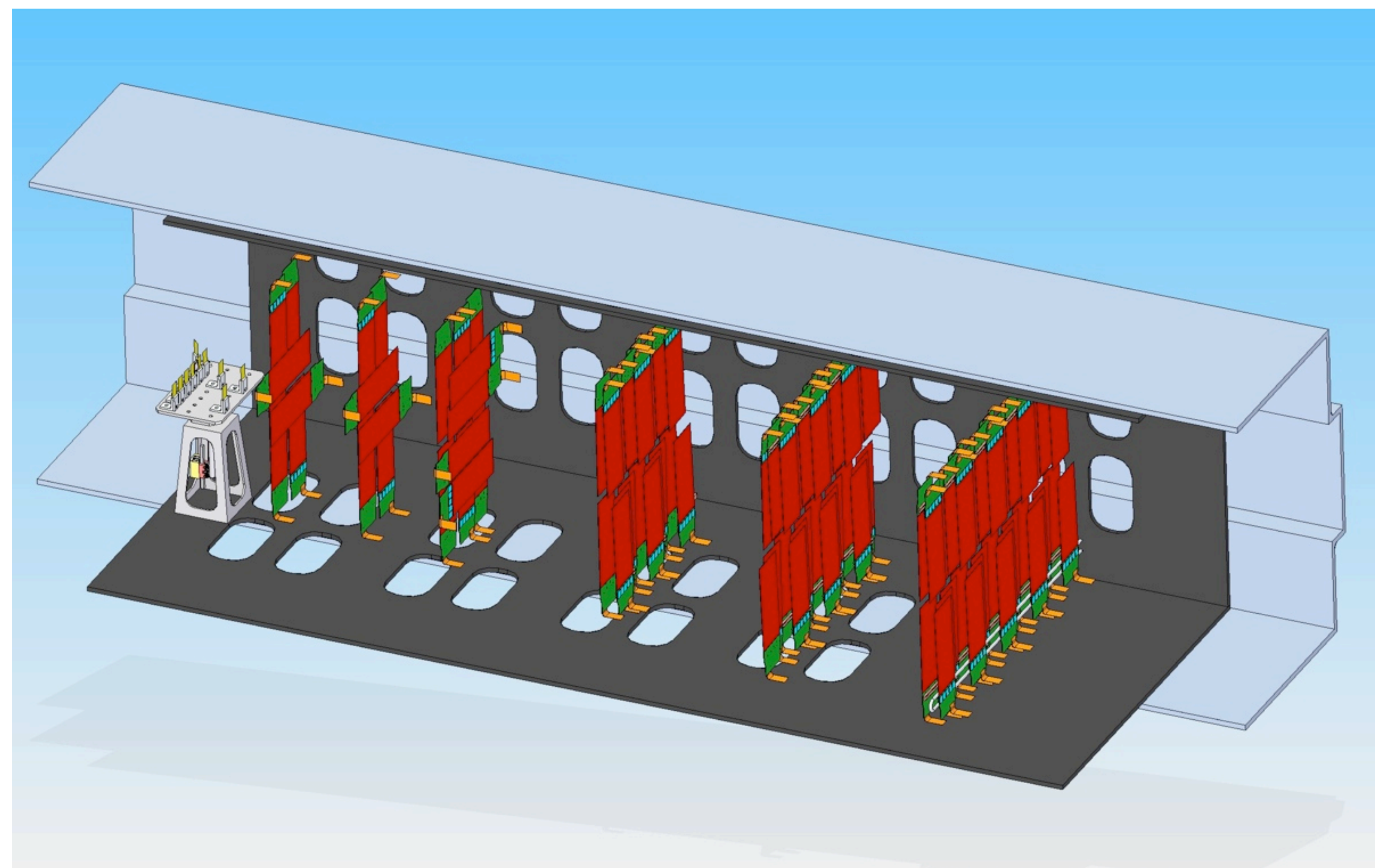
Placement of a tracking and vertexing system immediately downstream from a target and inside an analyzing magnet provides both measurements with high acceptance from a single, relatively compact detector.

Challenges

- At relevant beam energies and interesting A' masses, decay products tend to be electrons with momenta order a few GeV. Multiple scattering...
  - dominates both mass and vertexing measurement errors
  - leads to pattern recognition mistakes in dense environments
- Proximity to target means primary beam must pass through apparatus.
  - scattered beam sweeps out a “dead zone” of extreme occupancy and radiation, compounded by beam-gas interactions
  - puts low-mass acceptance in opposition to longevity and tracking purity
- Long-lived A' signal very small: vertexing must be exceedingly pure to eliminate fakes.
- Most attractive if can be done quickly and at minimal cost.

Challenges ⇒ Design Principles

- Mass and vertex resolution
  - low-mass construction
- Occupancies and radiation
  - fast, robust sensors / readout
  - movability / replaceability
  - operation in vacuum
- Acceptance/Purity
  - optimized sensor layout
- Schedule/Budget Sensitivity
  - reuse and recycle components and techniques

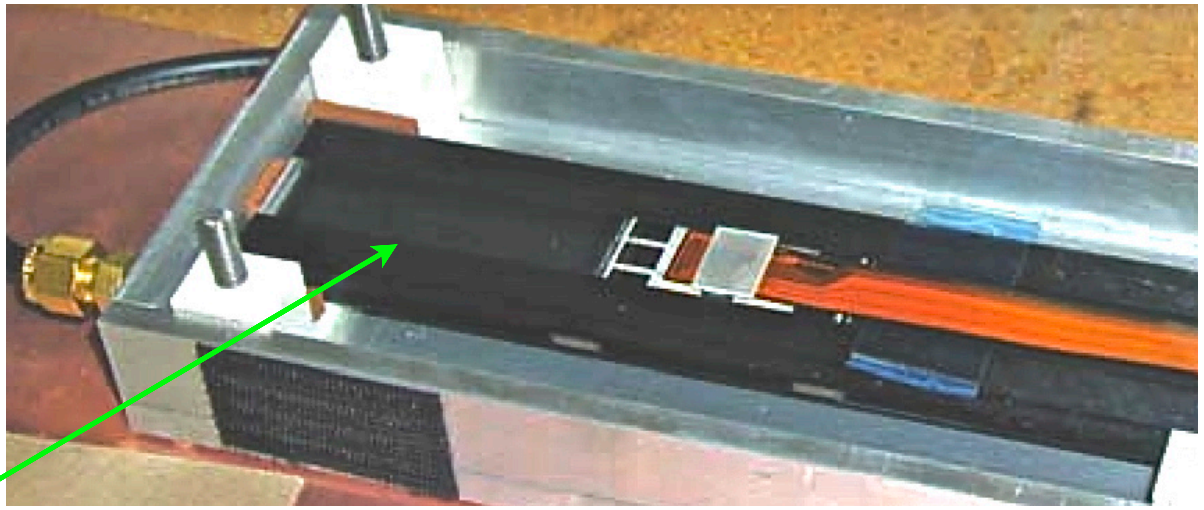


It's *easier* being green!

- silicon sensors
- readout ASICs
- hybrids
- support and cooling
- vacuum chamber

Silicon Sensors

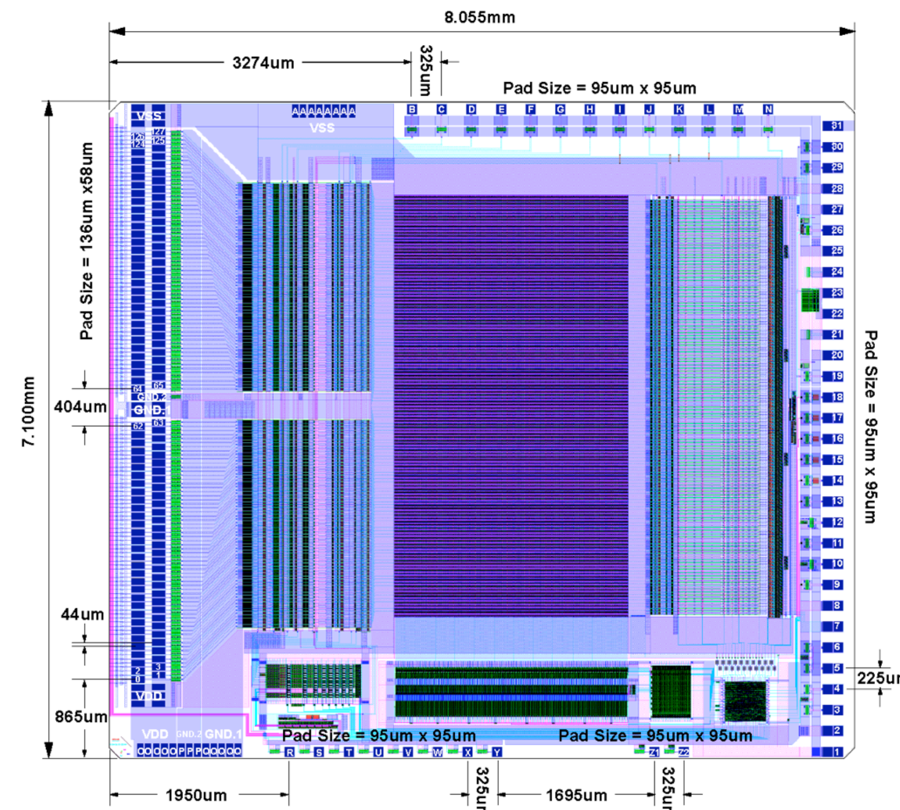
- pixels too massive, costly, complex: microstrips are the simple, lightweight solution
- Production Tevatron RunIIb sensors
  - Radiation tolerant: many capable of 1000V bias
  - Fine readout granularity
  - Readily available in sufficient quantity



Cut Dimensions (L×W)	100 mm × 40.34mm
Active Area (L×W)	98.33 mm × 38.34mm
Readout (Sense) Pitch	60μm (30μm)
# Readout (Sense) Strips	639 (1277)
Depletion Voltage	40V < V_{dep} < 300V
Breakdown Voltage	>350V
Total Detector Current at 350V bias	<16 μA
Bias Resistor Value (both ends of strips)	0.8 ± 0.3 MΩ
AC Coupling Capacitance	>12 pF/cm
Total Interstrip Capacitance	<1.2 pF/cm
Defective Channels	<1%

Readout Electronics: APV25

- Silicon readout for high rate environment: ***LHC***
- APV25 (CMS) is best of these for us.
  - Low noise: S/N ≈ 34 with our sensors
  - Radiation tolerant
  - Chips, DAQ infrastructure, knowledge; all widely available
  - ***Flexible in operation...***



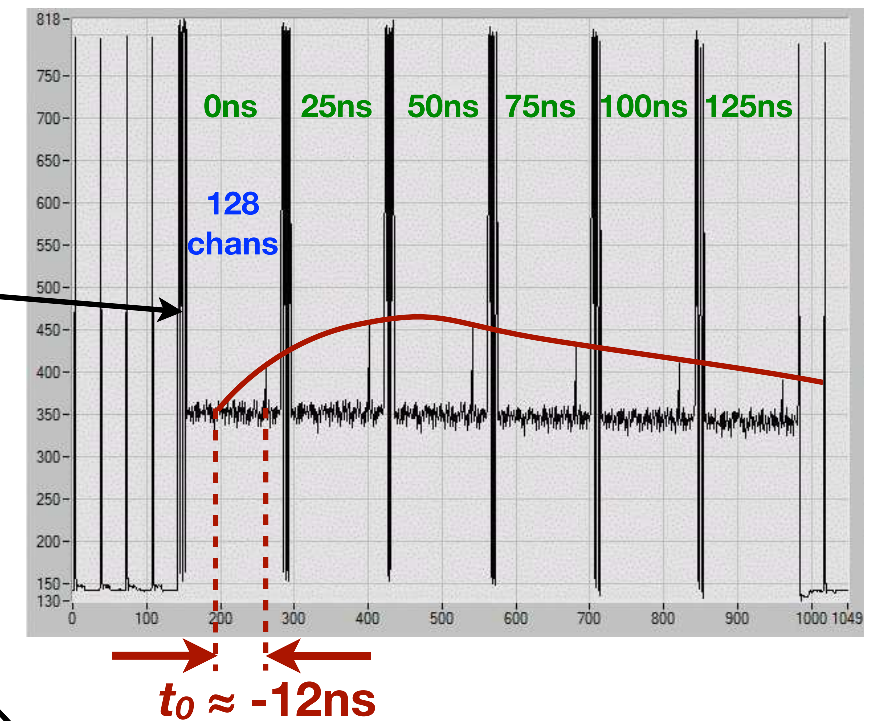
# Readout Channels	128
Input Pitch	44 μm
Shaping Time	50ns nominal (35ns min.)
Output Format	multiplexed analog
Noise Performance (multi-peak mode)	270+36×C(pF) e^- ENC
Power Consumption	345 mW
Communication Protocol	I^2C

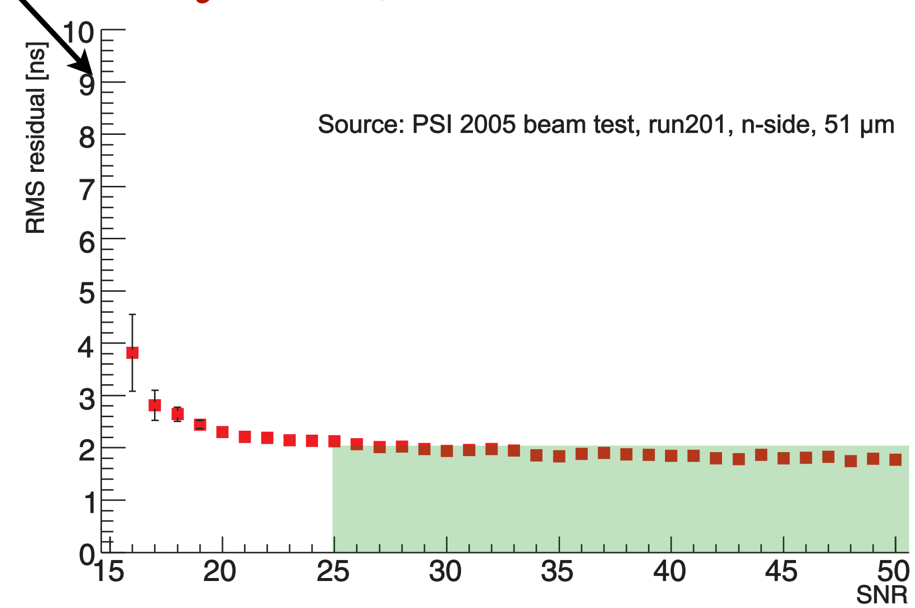
Timing Information

Multi-peak readout mode offers major reduction in background occupancy:

- Sample shaper output periodically after trigger to extract t_0: pioneered for Belle II.
- Fit to shaping curve determines hit time with RMS of ~2 ns or better for S/N > 25.
- 6-sample readout helps at high occupancy: de-convolute two hits in same shaping window
- For simulation studies, simply assume a 7.5ns time window for hits when tracking (~2σ cut).

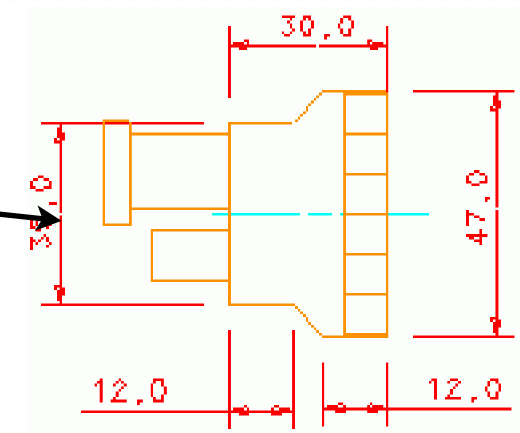
➡ Fitting tracks simultaneously in space *and* time will improve on this.

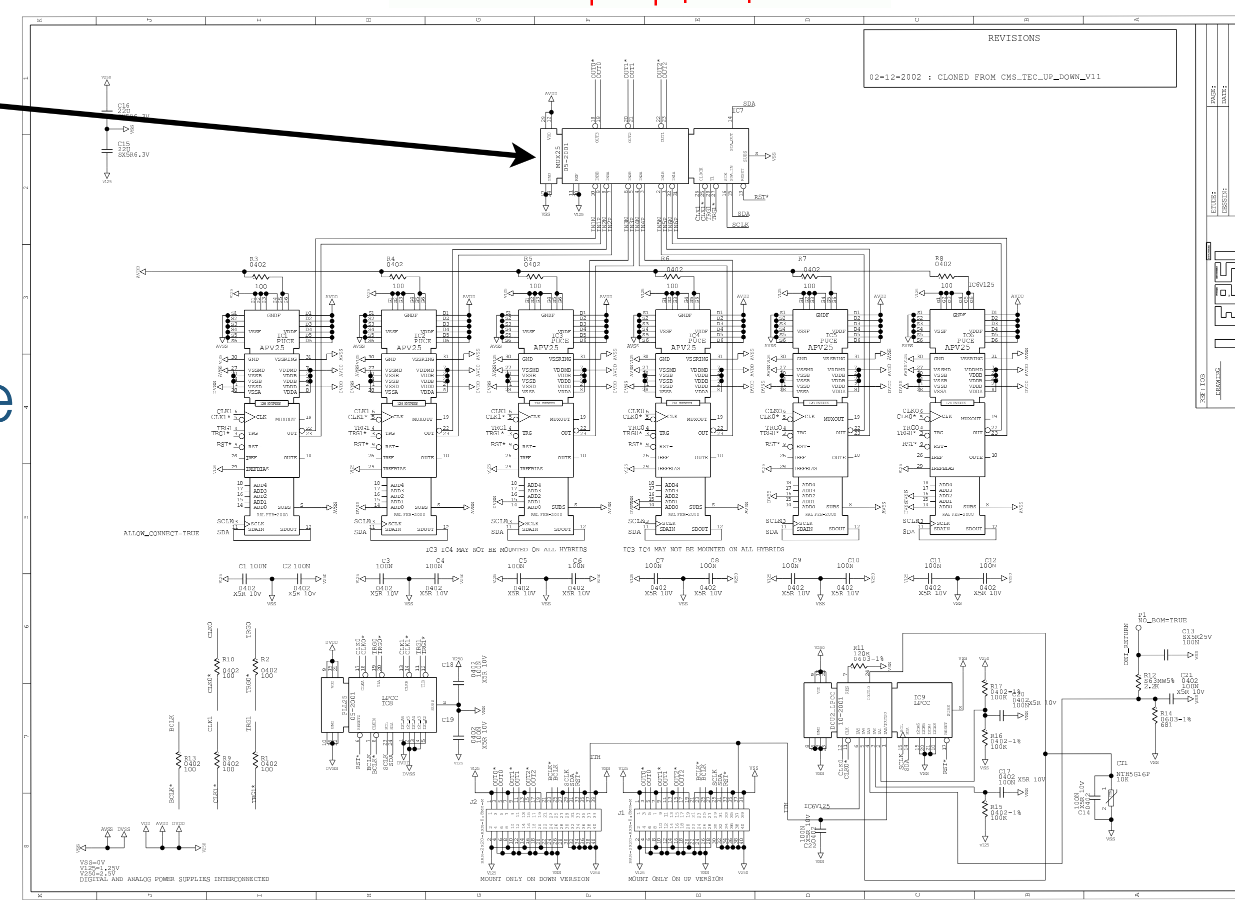




Hybrids

- Need something simple and compact: similar to CMS TIB hybrid, *but*...
  - 5 chips instead of 6 to match sensors
  - analog driver instead of APVMUX
  - *probably* no need for pitch adapter
  - *probably* no need for ceramic substrate
- Starting from CMS schematics, should be fairly simple
- Want prototype soon: critical path.

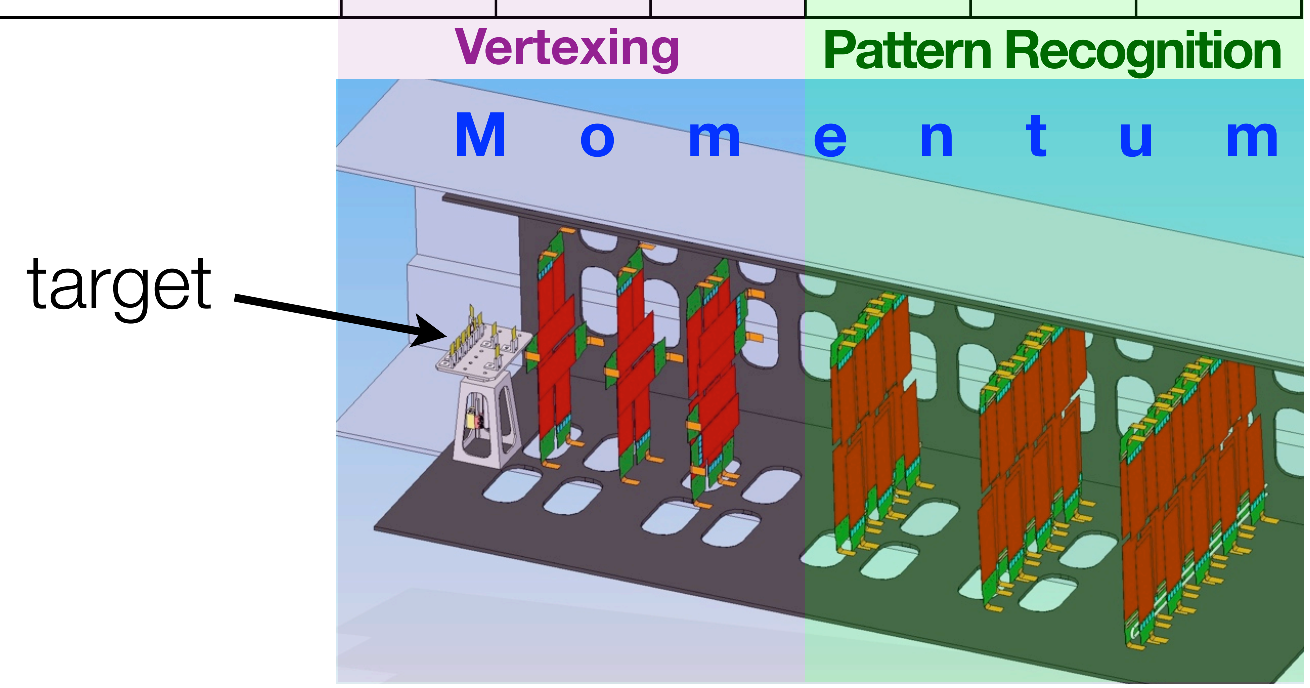




Detector Layout

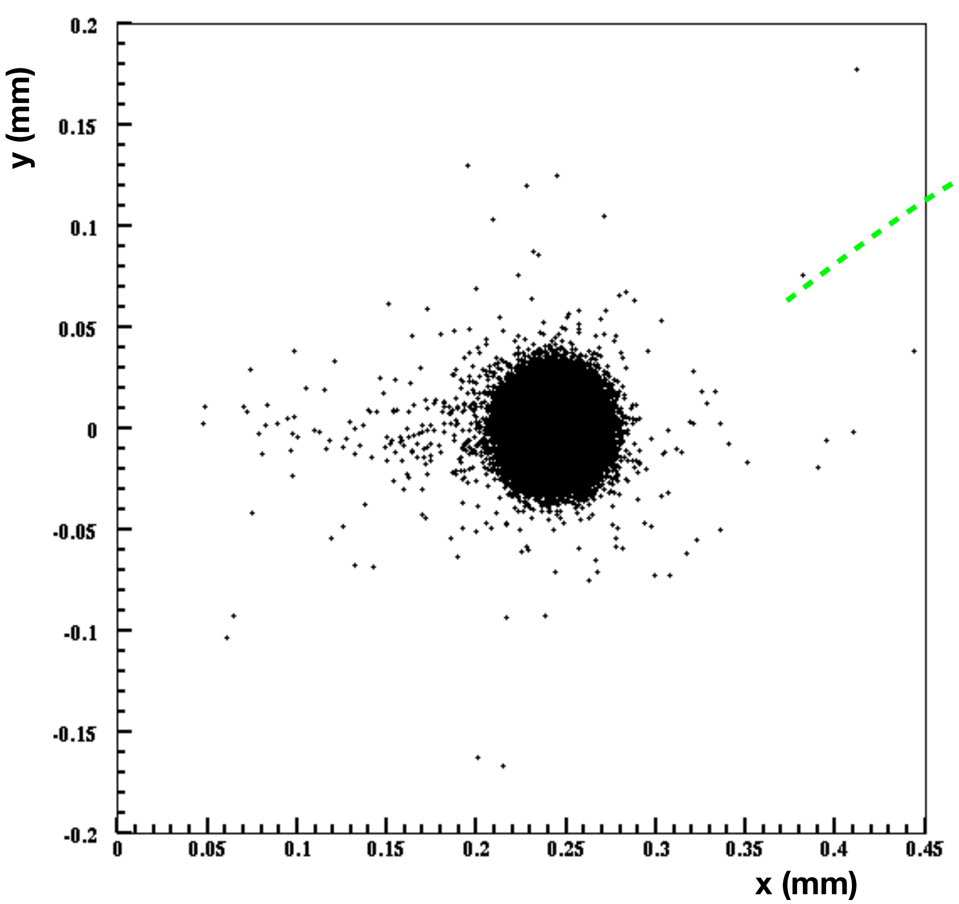
- Layers 1-3: vertexing
- Layers 4-6: pattern recognition with adequate pointing into Layer 2.
- Bend plane measurement in all layers: momentum
- 106 sensors/hybrids
- 530 APV25 chips
- 67840 channels

	Layer 1	Layer 2	Layer 3	Layer 4	Layer 5	Layer 6
z position, from target (cm)	10	20	30	50	70	90
Stereo Angle	90 deg.	90 deg.	90 deg.	50 mrad	50 mrad	50 mrad
Bend Plane Resolution (μm)	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6	≈ 6
Stereo Resolution (μm)	≈ 6	≈ 6	≈ 6	≈ 120	≈ 120	≈ 120
# Bend Plane Sensors	4	4	6	10	14	18
# Stereo Sensors	2	2	4	10	14	18
Dead Zone (mm)	±1.5	±3.0	±4.5	±7.5	±10.5	±13.5
Power Consumption (W)	10.5	10.5	17.5	35	49	63

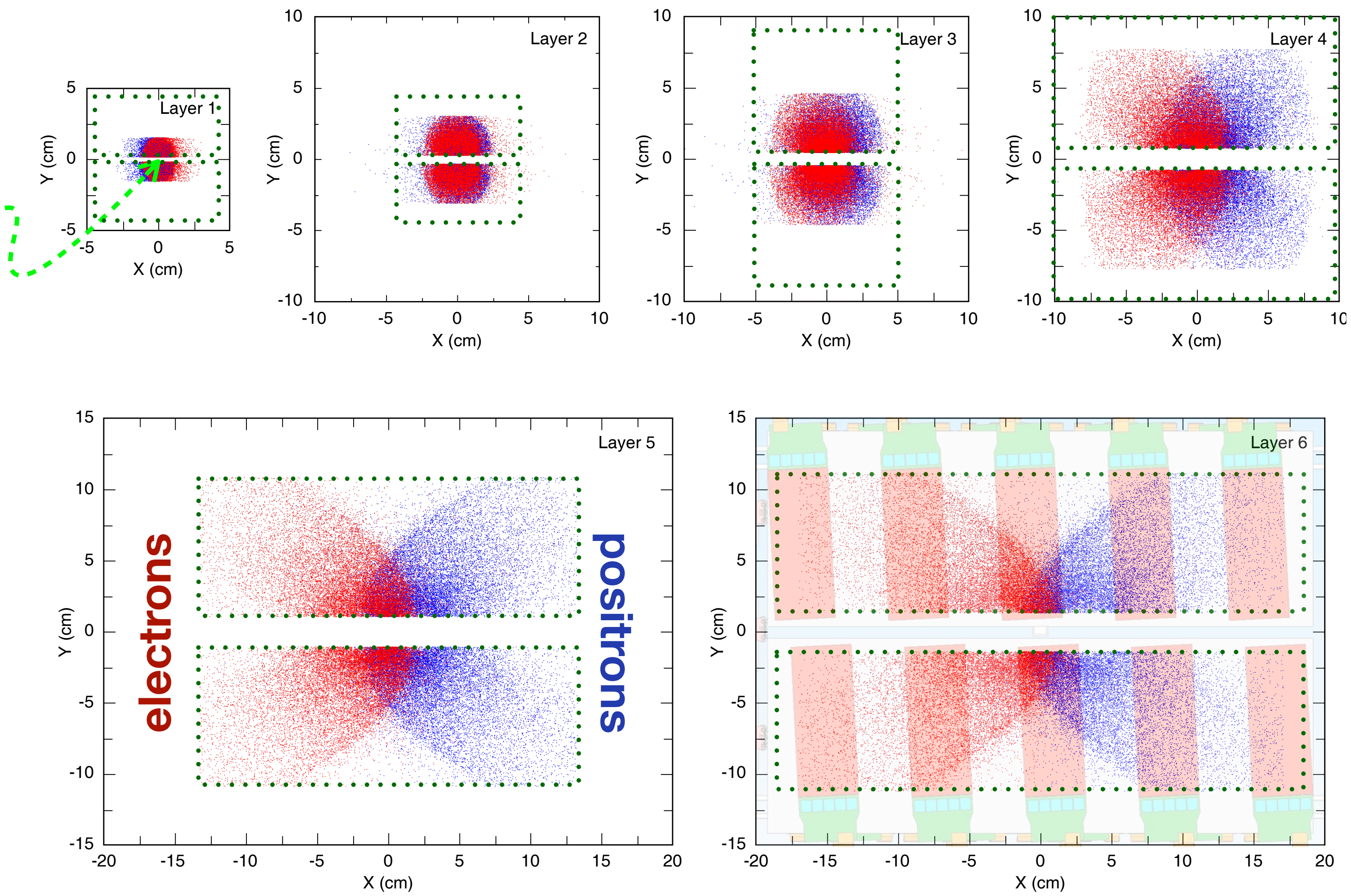


Dead Zone and Acceptance

75 ns of beam at Layer 1

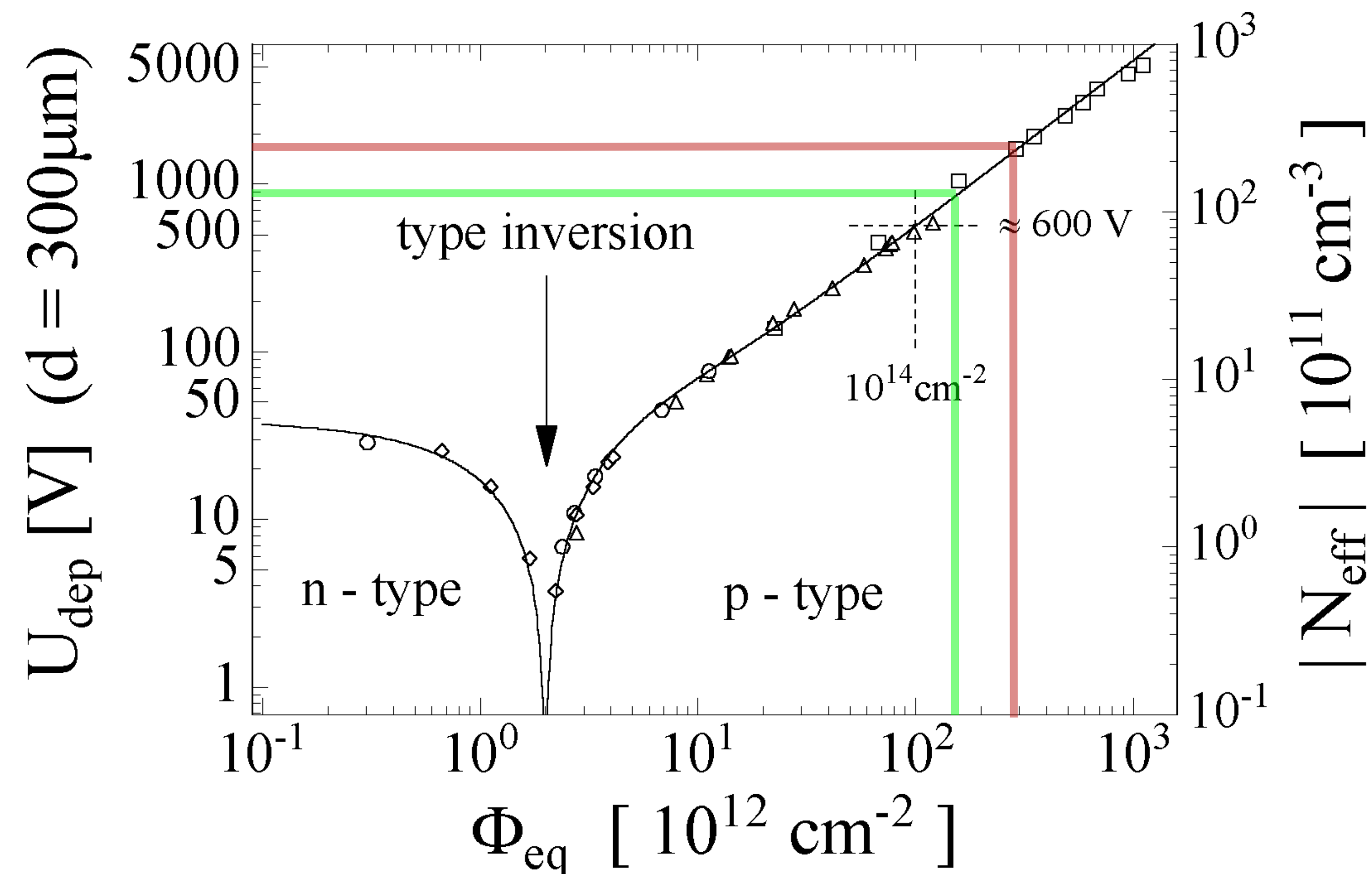


Hits from tracks within acceptance;
E_{beam}=5.5 GeV $m_{A'}$ = 300 MeV/c^2



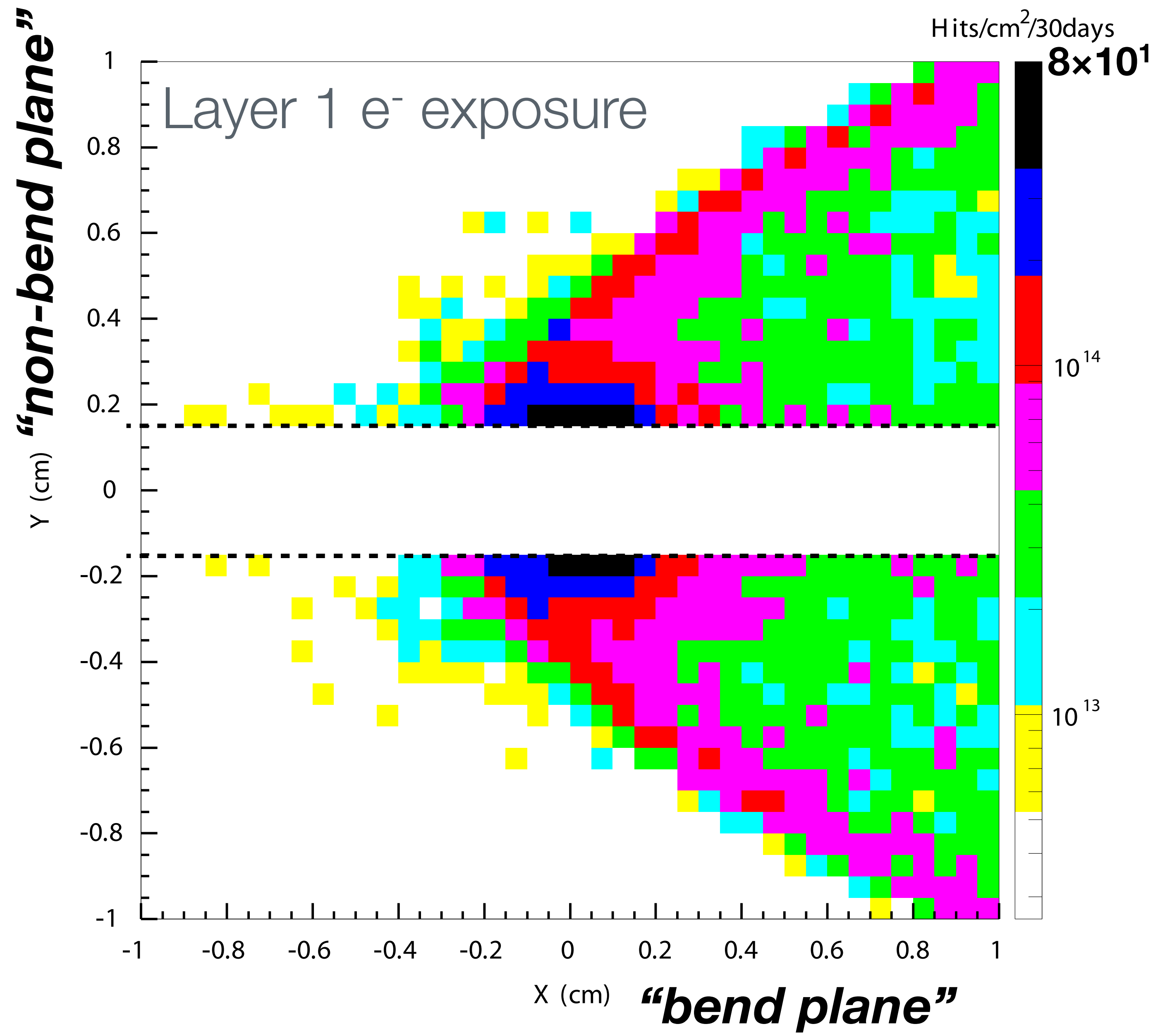
Dead Zone: Radiation Limit

- At V_{bias} = 1000V, sensors fully depleted up to Φ_{eq}>1.4×10^{14} cm^{-2} (1 MeV neutron equivalent dose)
- After that, a "soft landing," with lost signal degrading timing and resolution for Φ_{eq}>2.5×10^{14} cm^{-2}
- Electron damage is ~1/30 that of 1MeV neutrons: full depletion up to ~4×10^{15} e^-/cm^2



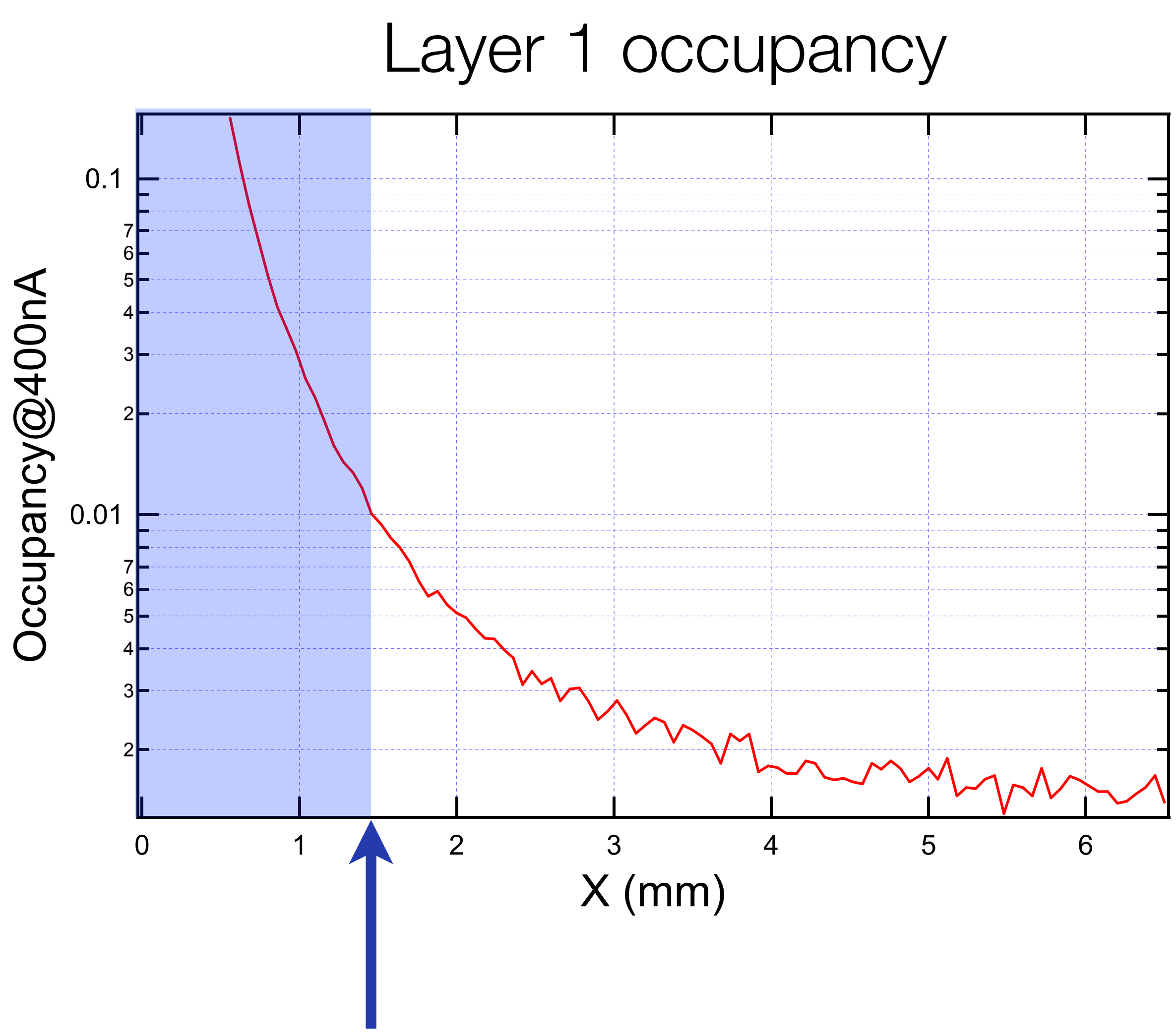
Dead Zone: Radiation Limit

- Want entire detector to remain fully depleted for 3 months $\Rightarrow \sim 1.4\times10^{15}$ e^-/cm^2 /month
- In first layer, conservative choice of dead zone is y < ±1.5mm
- In deeper layers, slightly more solid angle can be covered



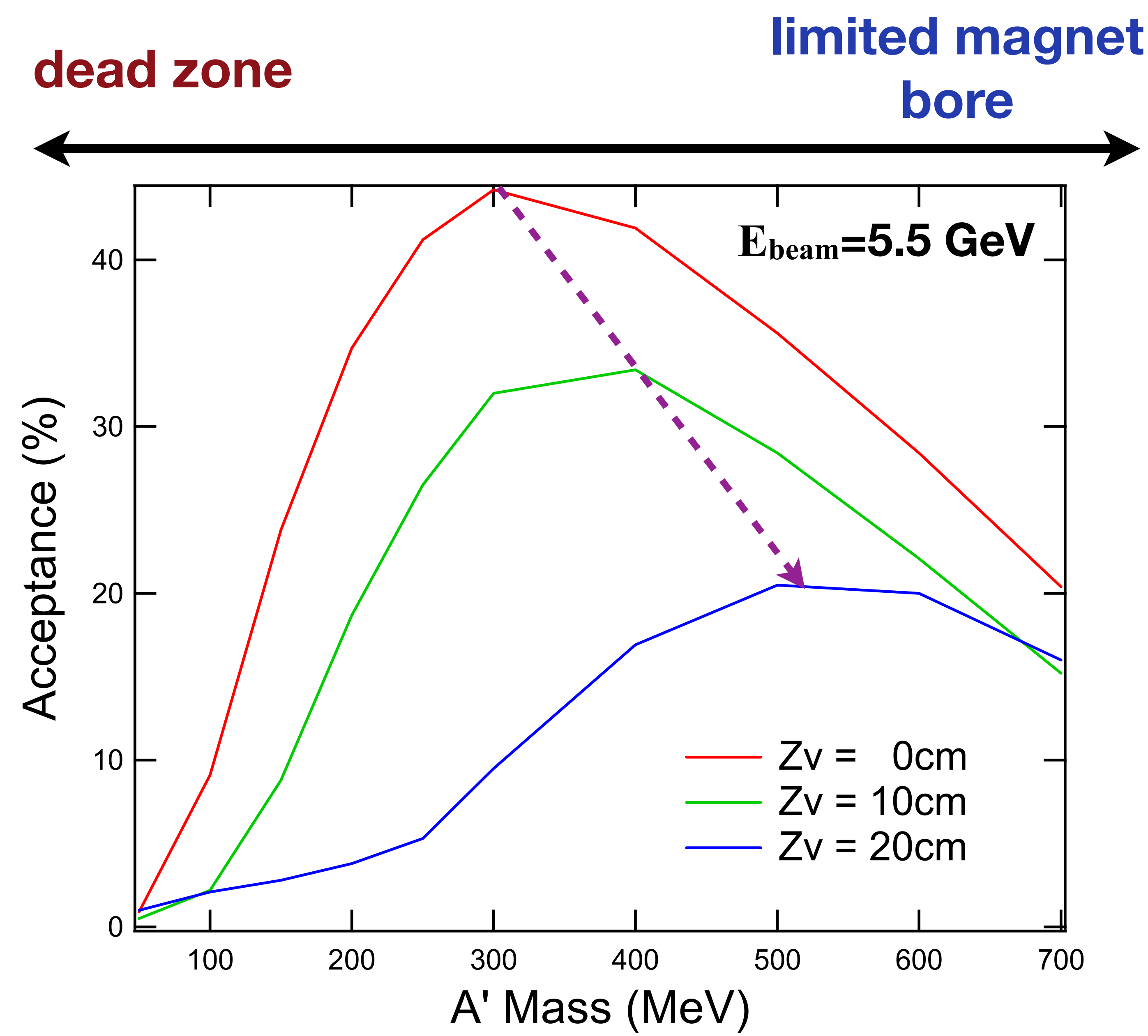
Dead Zone: Occupancy Limits

- For pattern recognition, want occupancy within our time resolution window of <1%
- ⇒ L1 dead zone y < ±1.4 mm.
- Results in L1 unanimous.
- Since z_{L1} = 10cm, implies 15 mrad dead zone for prompt decays. This configuration used for simulation studies and reach calculations.



Acceptance

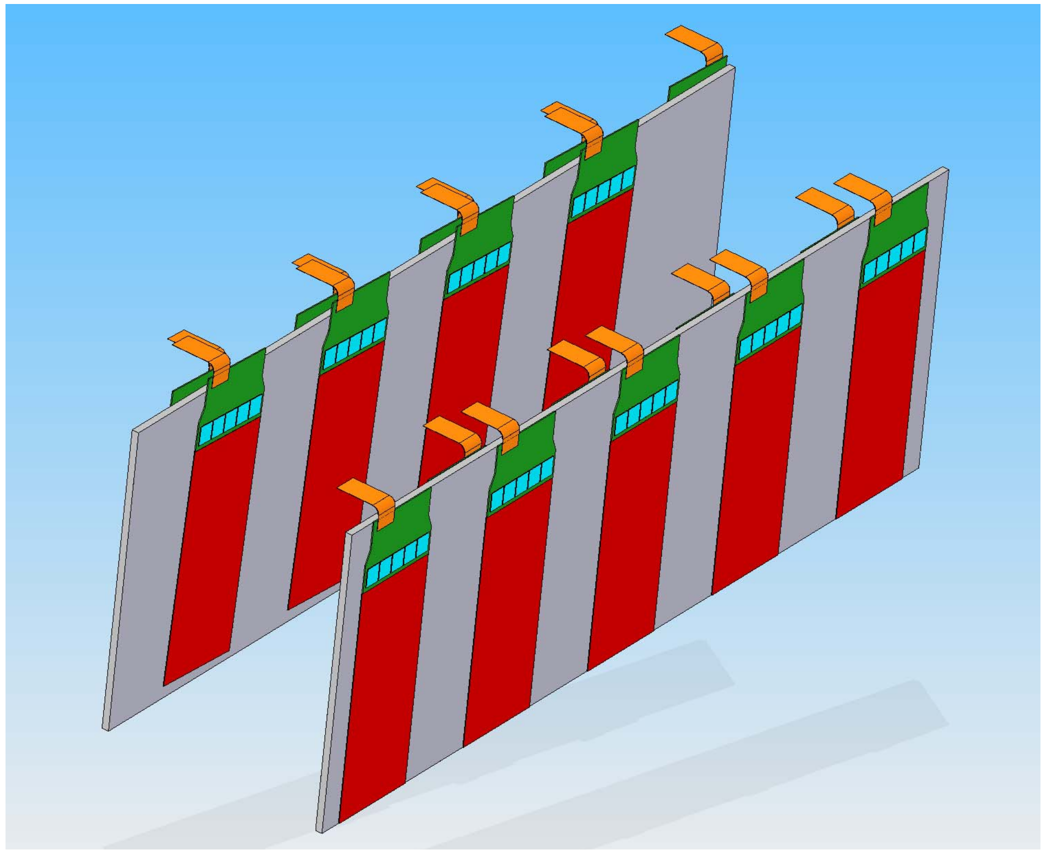
- At smaller masses, dead-zone limits acceptance
- At larger masses, losses due to limited coverage in layers 5 and 6 become important.
- Solid angle of dead zone increases with increasing z-vertex position
- May be possible to decrease dead zone in deeper layers to combat this if we can vertex cleanly without Layer 1

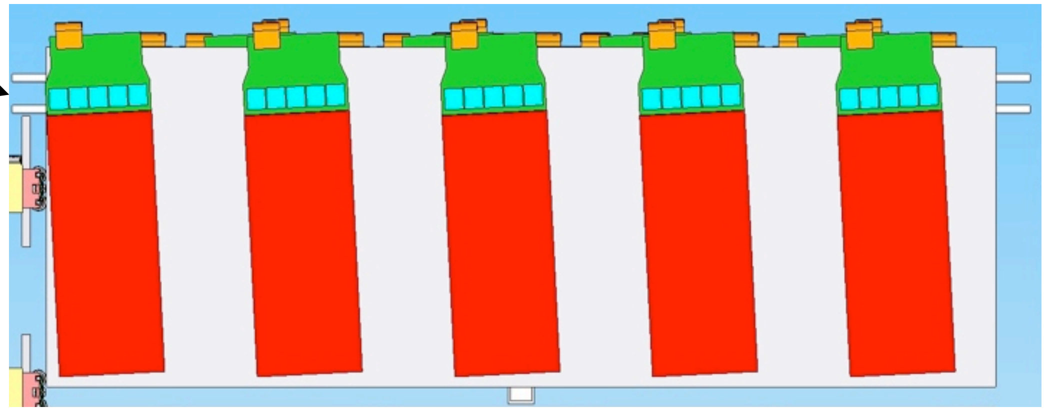


Support: Sensor Modules

Simple, familiar construction:

- silicon for each view on alternating sides of carbon-fiber-skinned, rohacell-foam sheet: each “layer” a stereo pair of modules on either side of dead zone.
- Voids in supports reduce material
- cooling tubes only under hybrids, water-glycol at -5°C.
- passivated pyrolytic graphite sheet under sensors isolates HV and increases lateral thermal conductivity





Material Budget

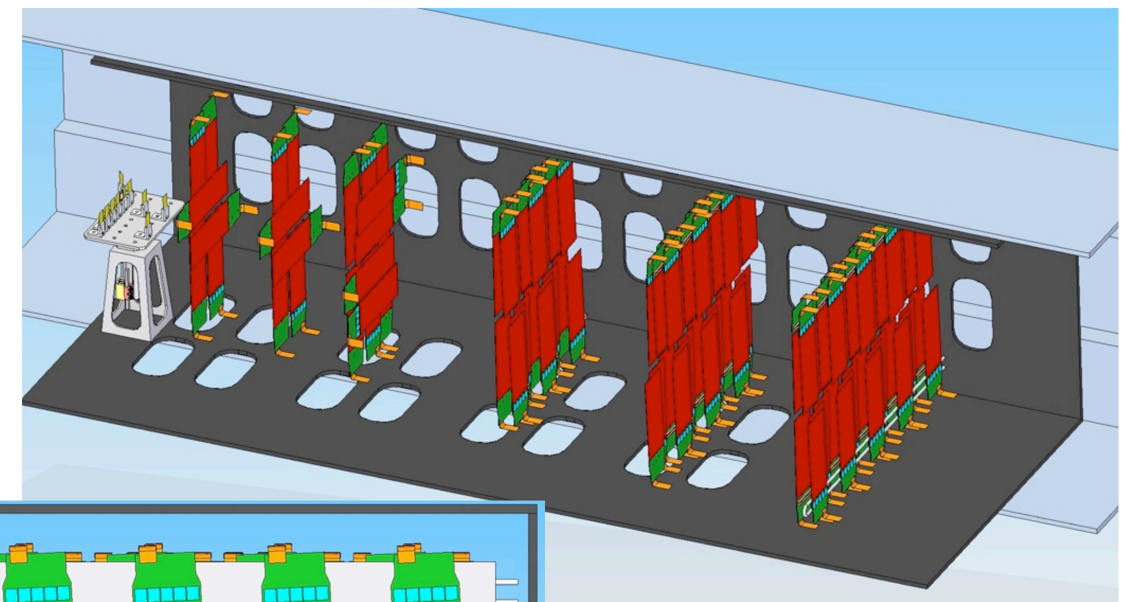
- ~1.0% X_0 / layer, including overlap regions
- dominated by silicon itself

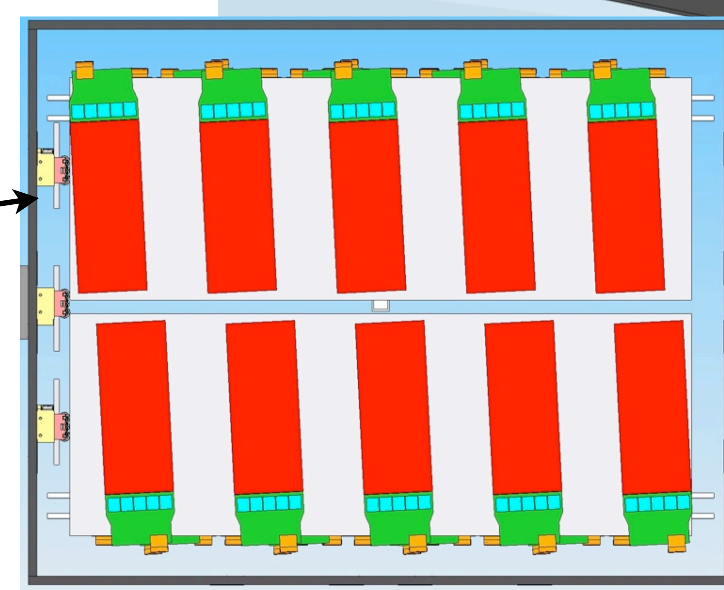
per measurement plane

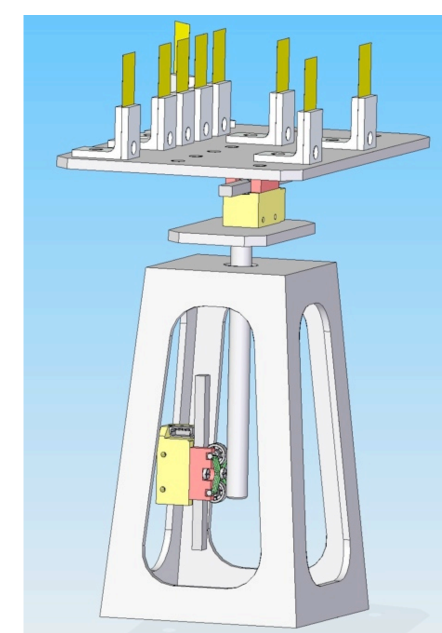
	Radiation Length (mm)	Thickness (mm)	Coverage/ Unit Acceptance	Scattering Material (% X_0)
Silicon	**93.6**	**0.320**	**1.2**	**0.410**
Rohacell Foam	13800	3.0	0.5	0.011
Carbon Fiber	242	0.150	0.5	0.031
PGS Passivation	256	0.101	1.25	0.049
Epoxy	290	0.050	0.5	0.009
Total	-	-	-	**0.510**

Support: Support Box

- similar CF/rohacell composite panels
- extension cables and cooling lines from hybrids and modules to patch panel on vacuum chamber pre-installed on support box
- Module mounts include a pair of piezo motors: allow retraction during uncertain beam conditions
- Supports target stand, including similar motion control system for target selection: nominal target is 0.25% X_0 tungsten.

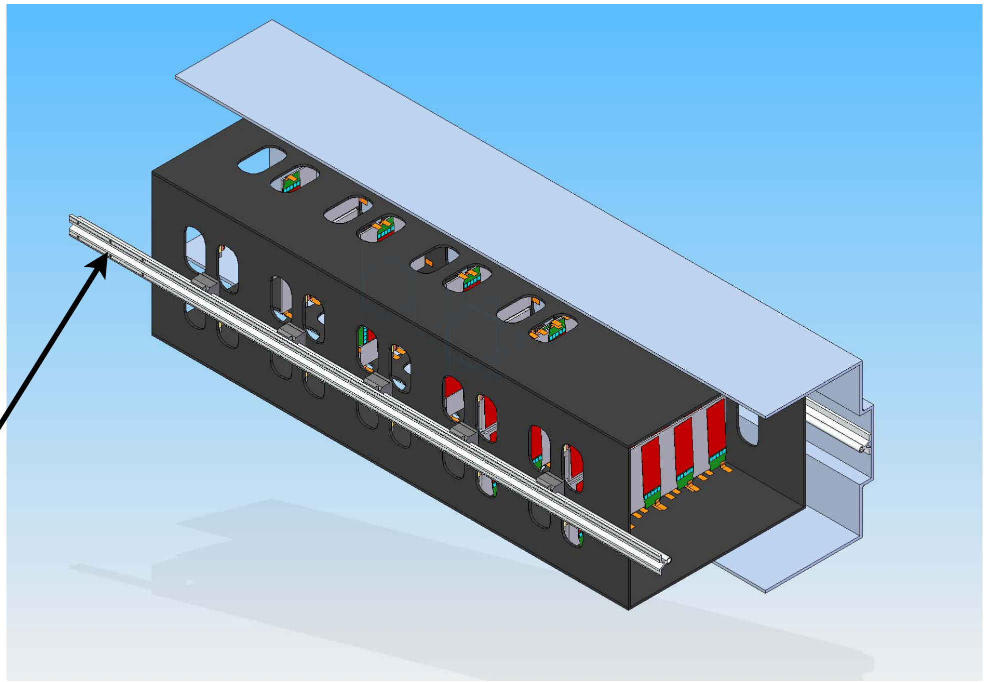


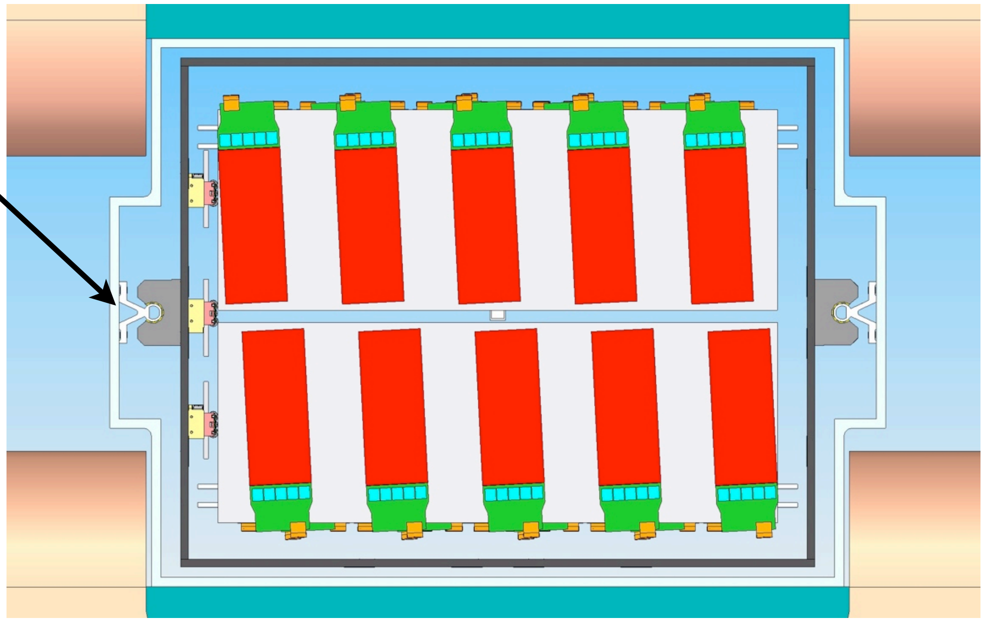




Support: Vacuum Chamber

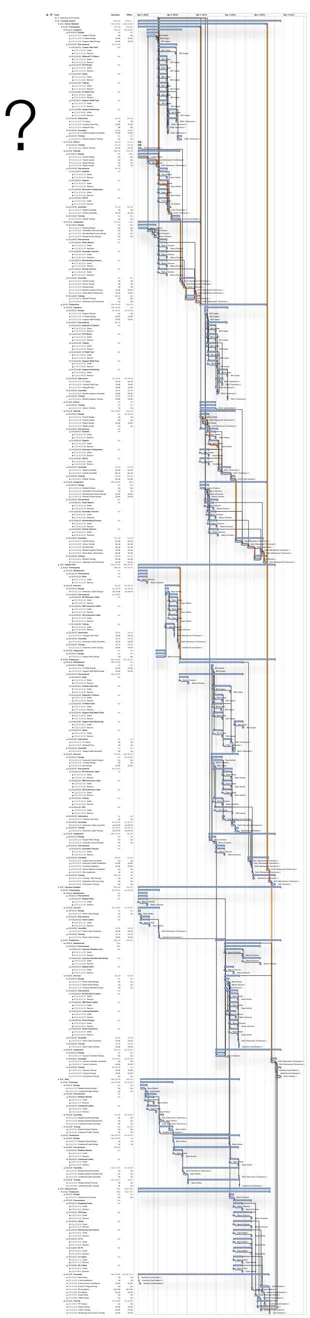
- vacuum chamber permanently captured inside magnet bore
- patch panel for cooling and cable connections at front face.
- linear rail system with carriages on support box for insertion and extraction of tracker
- Custom multi-layer insulation (MLI) blanket eliminates radiative heating: ~5W/module.
- Ensuring negligible heat load on silicon necessitates vacuum of ~10^{-4} Torr.





“I’ll Take One To Go, Please...”

Need new glasses??



- OK... it’s not a pizza, but it’s also not CMS!
- My own context: similar in scale/scope to CDF Layer 00: channel count, number of sensors/hybrids, budget and some unusual requirements, but less aggressive.
  - silicon already in hand.
  - no components/techniques need R&D.
- Believe it can be completed in a year.

“You and What Army?”

- **SLAC**: Tim Nelson, Marco Oriunno, Gunther Haller, Chris Kenney, ...
- **UCSC**: Alex Grillo, Ned Spencer, ...
- **FNAL**: Marcel Demarteau, Bill Cooper, ...
    - CDF RunII, D0 RunII and Run2b, CMS, ATLAS, CLEO-II, Babar, ILC, SDC... many decades of experience in the group!
    - Includes leading expertise in semiconductor devices, readout/DAQ, carbon fiber supports, cryogenics/vacuum: *everything* that is needed here.
    - Group consensus that schedule and budget are reasonable.

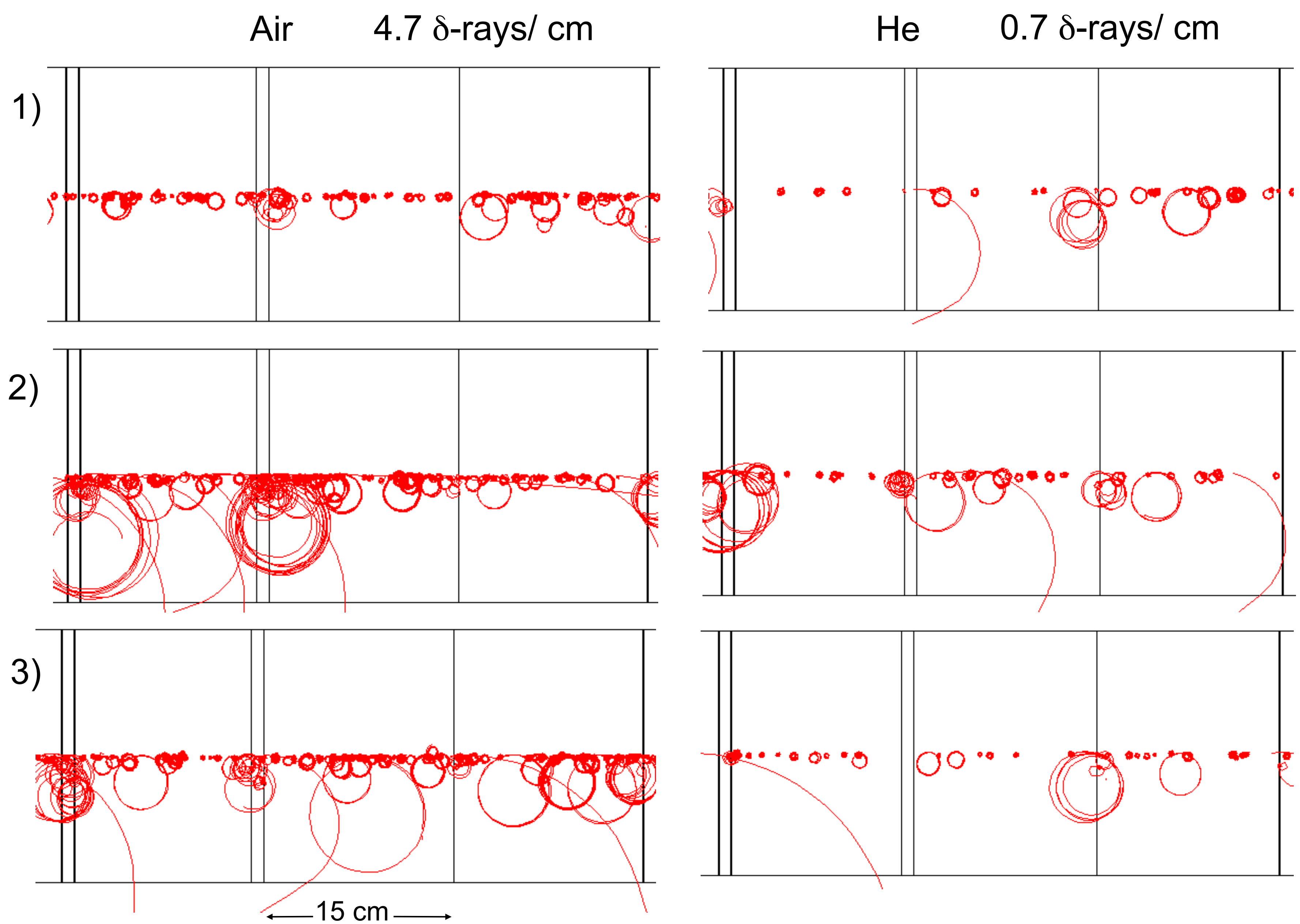
Summary

- A relatively small and simple tracker is all we need (see Matt's talk after lunch for review of how the system performs.)
- The most expensive and complicated components, sensors and readout ASICs, are well-developed and readily available free or at reasonable cost.
- Some unusual requirements (operation in vacuum, movable planes) will require careful attention.
- Time pressure is the biggest challenge. Important to get started as soon as possible and avoid unnecessary distractions and development by keeping things simple wherever possible.

Backup Slides

Why Vacuum?

δ-ray background in 25 ns



Upgrade?

Thin silicon in Layers 1 and 2?

- Reduces material budget by 0.15% X_0 / plane: 30% of total.
- S/N still ~22: timing resolution degrades by only ~10%.
- Cost: $37.5k for silicon per copy
- Should be possible to use same hybrids, partially populated, with a pitch adapter
- Additional risk for parts not in hand. Risk in working with Micron, but minimal for such a small production of single-sided sensors.