

## DEFINITIONS

- “causing things to *indicate* the same time” (clocking)  
“the relation that exists when things *occur* at the same time” (control)

## WHAT NEEDS TO BE SYNCHRONIZED

- RF reference signals (distribution, detection, feedback control)  
Fibre-based distribution, optical-to-RF conversion, lasers with low HF noise and the latest electronics have delivered <100fs and promise to get to ~10fs  
CPE stabilized lasers make clocks with 45as jitter from mHz to MHz !
- Laser pulses to RF  
Few hundred fs is commercially available, <100fs is not too hard and <1fs is state-of-the art (but the RF can't be too noisy, and people mustn't talk !)
- Electron bunches  
Phase jitters of  $0.03^\circ$  at 1.3GHz (65fs - Rossendorf),  $0.01^\circ$  at 1.5GHz (20fs – Cornell/Jlab), 150fs over >30 minutes (TTF) and <200fs sustained (Jlab) have all been measured

## WG4 SYNCHRONIZATION

### CHARGE

- Minimising LF ERL phase noise (e.g. thermal, vibrational, machine re-tuning)
- Minimising HF ERL phase noise (e.g. microphonics, HOMs, beam instabilities)
- Dispersion management
- Modelling (incl beam effects on RF synchronization)
- Frequency-domain and time-domain electron timing sensors
- Timing prediction without electrons (e.g. microphones for microphonics)
- Control systems (feedback, feed-forward, closed-loop, open-loop)
- Complex time structures (missing bunches, time-varying bunch charge)
- Fast (>kHz ?) actuators to control electron timing
- Beam-derived synchronization signals (vs LLRF distribution)
- RF distribution
- Laser stability

## WG4 SYNCHRONIZATION

### STATUS

- Most subsystems have been shown to work “routinely” with jitters of  $\sim 100$ fs and with comparable phase stability for times ranging from minutes to days
- With state-of-the-art subsystems  $\sim 10$ fs jitter has now either been achieved or could be achieved (given enough money) on timescale of 2-3 years
- Demonstration of  $\sim 100$ fs jitter across large (0.1-1km) integrated systems is within reach
- Synchronization of subsystem pairs to  $\sim 10$ fs jitter seems plausibly achievable
- Issues that remain include:
  - Long-term phase stability/referencing
  - Environment control (temperature, vibration, EM noise, radiation damage)
  - Maximizing time and frequency stability at the machine design stage
- The devil is in the detail !